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# UTILITY PATENT APPLICATION TRANSMITTAL (Large Entity) *(Only for new nonprovisional applications under 37 CFR 1.53(b))*	Docket No. MUR-8509US Total Pages in this Submission

jc598 U.S. PTO 04/10/00

jc682 U.S. PTO 09/546256 04/10/00

TO THE ASSISTANT COMMISSIONER FOR PATENTS
Box Patent Application
Washington, D.C. 20231

Transmitted herewith for filing under 35 U.S.C. 111(a) and 37 C.F.R. 1.53(b) is a new utility patent application for an invention entitled:

METHOD AND APPARATUS FOR SAMPLING FLUIDS FROM A WELLBORE

and invented by:

David Charles Howe and Kevin Fraser Robb

If a CONTINUATION APPLICATION, *check appropriate box and supply the requisite information:*

☐ **Continuation** ☐ **Divisional** ☐ **Continuation-in-part (CIP)** of prior application No.: ______

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Enclosed are:

Application Elements

1. ☒ Filing fee as calculated and transmitted as described below

2. ☒ Specification having **forty-three (43)** pages and including the following:

   a. ☒ Descriptive Title of the Invention
   b. ☐ Cross References to Related Applications *(if applicable)*
   c. ☐ Statement Regarding Federally-sponsored Research/Development *(if applicable)*
   d. ☐ Reference to Microfiche Appendix *(if applicable)*
   e. ☒ Background of the Invention
   f. ☒ Brief Summary of the Invention
   g. ☒ Brief Description of the Drawings *(if drawings filed)*
   h. ☒ Detailed Description
   i. ☒ Claim(s) as Classified Below
   j. ☒ Abstract of the Disclosure

UTILITY PATENT APPLICATION TRANSMITTAL (Large Entity) *(Only for new nonprovisional applications under 37 CFR 1.53(b))*	Docket No. MUR-8509US
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Application Elements (Continued)

3. ☒ Drawing(s) *(when necessary as prescribed by 35 USC 113)*
   - a. ☐ Formal — Number of Sheets ______
   - b. ☒ Informal — Number of Sheets sixteen (16)
4. ☒ Oath or Declaration
   - a. ☒ Newly executed *(original or copy)* ☐ Unexecuted
   - b. ☐ Copy from a prior application (37 CFR 1.63(d)) *(for continuation/divisional application only)*
   - c. ☒ With Power of Attorney ☐ Without Power of Attorney
   - d. ☐ *DELETION OF INVENTOR(S)*
     Signed statement attached deleting inventor(s) named in the prior application, see 37 C.F.R. 1.63(d)(2) and 1.33(b).
5. ☐ Incorporation By Reference *(usable if Box 4b is checked)*
   The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4b, is considered as being part of the disclosure of the accompanying application and is hereby incorporated by reference therein.
6. ☐ Computer Program in Microfiche *(Appendix)*
7. ☐ Nucleotide and/or Amino Acid Sequence Submission *(if applicable, all must be included)*
   - a. ☐ Paper Copy
   - b. ☐ Computer Readable Copy *(identical to computer copy)*
   - c. ☐ Statement Verifying Identical Paper and Computer Readable Copy

Accompanying Application Parts

8. ☐ Assignment Papers *(cover sheet & document(s))*
9. ☐ 37 CFR 3.73(B) Statement *(when there is an assignee)*
10. ☐ English Translation Document *(if applicable)*
11. ☐ Information Disclosure Statement/PTO-1449 ☐ Copies of IDS Citations
12. ☐ Preliminary Amendment
13. ☒ Acknowledgment postcard
14. ☒ Certificate of Mailing
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UTILITY PATENT APPLICATION TRANSMITTAL (Large Entity)

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Total Pages in this Submission

Accompanying Application Parts (Continued)

15. ☐ Certified Copy of Priority Document(s) *(if foreign priority is claimed)*

16. ☒ Additional Enclosures *(please identify below)*:

Permit to File Abroad from European Patent Office

Fee Calculation and Transmittal

CLAIMS AS FILED

For	#Filed	#Allowed	#Extra		Rate	Fee
Total Claims	19	- 20 =	0	x	$18.00	$0.00
Indep. Claims	2	- 3 =	0	x	$78.00	$0.00
Multiple Dependent Claims (check if applicable) ☐						$0.00
					BASIC FEE	$690.00
OTHER FEE ***(specify purpose)***						$0.00
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Dated: **April 10, 2000**

cc:

CERTIFICATE OF MAILING BY "EXPRESS MAIL" (37 CFR 1.10) Applicant(s): **David Charles Howe and kevin Fraser Robb**		Docket No. **MUR-8509US**	
Serial No. **(to be assigned)**	Filing Date **(herewith)**	Examiner	Group Art Unit

Invention: **METHOD AND APPARATUS FOR SAMPLING FLUIDS FROM A WELLBORE**

I hereby certify that this Utility Patent Application Transmittal with listed enclosures
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Title of the invention: Method and apparatus for sampling fluids from a wellbore.

Background to the invention:

This invention relates to a method and apparatus for sampling fluids from a wellbore, and in particular to a method and apparatus used to recover a quantity of production fluids such as produced oil, gas and/or water from the wellhead of an underwater well.

Wells for hydrocarbons and other valuable fluids are normally drilled in a cluster with a number of wellbores having their surface wellheads grouped together. The wellbore may diverge away from each other the deeper they become. The wellheads in a group of wells are typically connected to a manifold or other subsea structure via conduits, and the hydrocarbons recovered from each individual well are conveyed along the conduits to the manifold where they usually co-mingle before flowing along a single main pipeline to the production platform. The quality and quantity of the fluids produced from each well may vary; for example, one wellbore may produce production fluids that are rich in crude oil and relatively free from

produced water and corrosive gasses such as H_2S, whereas a neighbouring well drilled to a different depth in the same formation may produce more water, or may have a high content of noxious and corrosive gasses; such a well would be less economically productive and may have higher maintenance costs. Furthermore, different wells tied back to the same manifold may be owned and/or operated by different operators. It is therefore useful to know the quantity and quality of wellbore fluids that are produced from each respective wellbore before they are mixed in the manifold or main pipeline leading from the manifold to the production platform, so that the relative benefits and liabilities of the respective wells can be calculated.

Traditionally this has been done by sampling the fluids produced at each respective wellbore by providing separate sampling conduits or lines that run parallel to (and usually along the outside of) the conduits between the respective wellbores and the manifold, and from there along the main pipeline back to the production platform, where they can be analysed and graded. Separate sampling lines are of course needed for each wellbore, and this causes several problems in that the additional small bore lines often become blocked by viscous fluids and cuttings, or damaged by corrosive agents like H_2S, and to address this several lines are normally installed for each wellhead all the way back to the platform, so that backup lines can be brought into operation if the main sampling line for a particular wellhead fails or becomes blocked. This is very expensive and the infrastructure of the extra

lines needs to be installed at the beginning of the life of a well, but is seen as the only solution to the problems of being able to sample continuously throughout the life of the well.

Summary of the Invention:

According to the present invention there is provided a method for sampling a fluid from a wellbore, the method comprising

a vehicle having a drive means for moving the vehicle, a collecting device for collecting a sample of the fluid and a storage facility for the collected fluid;

using the collecting device to recover a sample of the fluid to the vehicle's storage facility at a first location on a subsea structure;

storing the sample in the storage facility of the vehicle; and

carrying the sample in the vehicle's storage facility to a second location.

The present invention also provides a sampling device for collecting samples of fluid produced from a subsea wellbore, the sampling device having;

a drive means for moving the sampling device, a collection device for collecting a sample of fluid and a storage container for holding the collected fluid.

The first location is typically a wellhead but can be other positions of a well such as a wellbore, pipeline from the wellhead, side-track manifold, or main

pipeline, storage tank or gravity base structure. The first position typically has a collection port to mate with the collection apparatus. The second position can be onshore, underwater or on a platform or ship such as a remotely operated vehicle or "ROV".

Preferably the vehicle is an ROV. Preferably the storage tank and collection device are housed on a frame or skid attached to the ROV. Typically the collecting device comprises at least one sampling bottle, but two or more can be provided.

Typically the vehicle is adapted to interface with the wellhead at the first position, and can be provided with a collecting and sampling probe for insertion into e.g. an aperture on the wellhead. The probe can be connected to the storage tanks or bottles etc by means of conduits. Typically production fluids are extracted via the male/female connection between the probe and the aperture. The collecting device can be arranged to collect and discard a portion of the fluids being sampled, and typically recovers an initial sample of fluid from the collection port of the wellhead to a first sampling bottle. This is done because the fluid lying in the collection port of the wellhead may be static and may not represent a true sample of the fluid flowing through the wellhead. Therefore, the first sample of fluid from the collection port of the wellhead is drawn off to a first sampling bottle and can be kept separate from later samples. Any number of later samples e.g. 3-10 can be taken from the fluid flowing through the wellhead, depending on the number

of sampling bottles or partitions in the collection tank that are available. Typically a waste tank is provided at the second position into which the initial samples of static fluid can be discarded.

Typically the vehicle has an array of valves which can be activated independently of each other. Typically different configurations of the valves will direct liquid into each sampling bottle as required.

Typically the sampling bottles each contain a piston. Normally a pressure gauge is connected to each sampling bottle. Normally a piston indicator is provided so the position of the piston can be determined from a remote position outside the bottle. Typically the piston indicator moves with the piston, but it may be an electronic indicator that is monitored elsewhere on the ROV or remote from it. Typically the piston indicator is a rod which extends from the piston outside the bottle. Typically the sampling bottles are connected to the male connector via a hose of e.g. 1/4" diameter. The sampling bottles, valves and hose are typically designed to operate in pressures of up to 230 barg and at temperatures of -50 to 130°C.

During transportation of the ROV prior to use, the sampling apparatus is typically filled with a liquid. Preferably the liquid is bio-degradable. Typically the liquid is a mixture of water and glycol.

Typically the liquid is contained in the sampling bottles when the vehicle dives. Typically the liquid is expelled from a second end of the sampling apparatus

as fluid is recovered from the wellhead. Preferably a control means such as a throttle is provided on the second end of the sampling apparatus to control the rate of expulsion of the liquid. This typically controls the rate of introduction of the fluid from the wellhead into the first end of the sampling apparatus, typically via the piston.

When production fluids have been extracted from the first wellhead the vehicle typically disengages the probe from the collection port on the wellhead and moves (in ROV terminology it "flies") to the second position. The second position can typically be an offshore platform, a ship or an inshore facility. The vehicle typically docks at the second position where the sample(s) collected may be removed by e.g. removing the sampling bottles and replacing them with empty bottles. Typically only the second and subsequent sampling bottles are replaced. Typically the fluid(s) contained in the second or further sampling bottle is analysed for fluid chemistry.

In several important embodiments of the invention the collection device has several separate containers such as bottles for collecting samples and the vehicle flies between adjacent wellheads to collect samples from each of them before returning to the ship or platform etc for analysis of the samples. In this embodiment the vehicle can collect different samples from adjacent wellheads on a single trip.

While the ROV can be typically tied back to a ship or platform by a conventional umbilical the vehicle need not be a conventional ROV.

Typically the fluids contained in the first sampling bottle will be released into the waste tank. Normally this operation is performed at the second position. Typically a particular combination of open and closed valves can be used to direct fluids from any sampling bottle to the waste tank.

The pipework is typically vented before the sampling bottles are removed. This typically allows the pressure in the pipework to be equilibrate with ambient pressure and so ease the removal of the sampling bottles from the vehicle. Typically a particular configuration of the valves can be used to vent the pipework. After the pipework has been vented the sampling bottle(s) may be removed.

A new bottle is typically attached to the sampling apparatus. Typically the sampling apparatus is flushed with de-mineralised water to prevent cross-contamination between samples. Typically the sampling apparatus is purged with nitrogen prior to a subsequent sampling run in order to remove air from the pipework. Typically the sampling apparatus will be tested for leaks whenever a sampling bottle has been replaced.

Typically the vehicle (or at least the collection device) will undergo a hydrotest before a second

operation. In the hydrotest the sampling bottles are filled with de-mineralised water and pressurised up to 230barg. If no leaks or change in pressure are observed after a period in the order of 30 minutes the vehicle is typically subjected to a gas test. During the gas test, the vehicle (or at least the collection device) is typically submerged in a water bath and is flushed with Nitrogen gas through the probe to subject the sampling apparatus to a pressure of up to 125 barg. Any leaks would clearly be observed in the form of bubbles escaping from the vehicle or collection device.

<u>Brief description of the drawings:</u>

An embodiment of the invention will now be described by way of example only with reference to the accompanying drawings wherein;

Fig. 1 is a drawing of the sampling equipment;

Fig. 2a is a drawing of the sampling equipment during the hydrotest;

Fig. 2b is a drawing of the sampling equipment during the gas test;

Fig. 3 is a drawing of the sampling equipment during the system purge;

Fig. 4a is a drawing of the sampling equipment during transportation;

Fig. 4b is a drawing of the spare sampling bottle during the transportation;

Fig. 5 is a drawing of the sampling equipment prior to diving;

Figs. 6a to 6d are drawings of the sampling equipment after docking at the panel;

Fig. 7 is a drawing of the sampling equipment at the start of the sampling operation;

Fig. 8 is a drawing of the sampling equipment during operation;

Fig. 9 is a drawing of the sampling equipment after operation;

Fig. 10 is a drawing of the sampling equipment during venting of the first sampling bottle;

Fig. 11. is a drawing of the sampling equipment during purging of the sampling bottle with water/glycol;

Fig. 12 is a drawing of the sampling equipment prior to removal of the second sampling bottle;

Fig. 13 is a drawing of the sampling equipment during removal of the second sampling bottle;

Fig. 14 is a drawing of the sampling equipment during the flushing operation after insertion of a fresh sampling bottle;

Fig. 15 is a drawing of the sampling equipment during the during the purging operation after insertion of a fresh sampling bottle;

Fig. 16 is a drawing of the sampling equipment containing nitrogen;

Fig. 17 is a drawing of the sampling equipment during the a leak test;

Fig. 18 is a general arrangement of a skid containing the collecting device;

Fig. 19 is a selection of view of the fig.18 skid attached to an ROV;

Fig. 20 is a general arrangement showing the tools attached to the ROV;

Fig. 21 is a drawing of the slops tank;

Fig. 22 is a drawing of a sampling bottle; and,

Fig. 23 is a drawing of a sampling skid control console.

Detailed description of the drawings:

Referring now to the drawings, a collection device has a first sampling bottle 10 connected between valves 11-15 at the back end 27 of the bottle 10, and valves 17-20 at the front end 28. A second sampling bottle 110 is provided adjacent to the first 10 and is connected between valves 111-115 at the back 127 of the bottle 110 and valves 117-120 at a front opposite end 128. The valves 20, 120 are connected together by line 21. Pressure gauges 29, 129(not shown in all Figs) are provided for each sampling bottle 10, 110. A piston 16, 116 is provided inside each sampling bottle 10, 110. Rods 39, 139 shown in Fig. 1 (but omitted from the other figures for clarity) are attached to and move with the pistons 16, 116. Each rod 39, 139 extends from a respective piston 16, 116 through the back of a respective bottle 28, 128 and so provides a means to determine the position of the pistons inside the sampling bottles. The rods can be sealed against the ends of the bottles by o-rings etc (not shown).

In the drawings, a black-shaded valve indicates the valve is closed, while an unshaded valve indicates the valve is open. A valve shaded in grey indicates the

valve is partially open. Valves 15, 115 remain partially open throughout all operations and so will not be referred to again.

The collection device is disposed in a frame or "skid" 60 that is connectable to the base of an underwater vehicle or ROV 200. The ROV 200, as is conventional in the art, typically has a motor (not shown) to move the skid between first and second positions, and an umbilical line connecting the ROV 200 to the operating station. Typically the umbilical line comprises a cable to power the hydraulic and electrical systems on the ROV 200 and any other cables such as those connected to onboard cameras.

A tool deployment unit (TDU) or XYZ tool position unit 80 is attached to the ROV 200 as shown in Fig. 19b. The TDU 80 may comprise various tools like grabs, cameras, docking probes and sockets to facilitate docking of the ROV 200 with a manifold etc and can move in a vertical, horizontal and fore-aft direction relative to the ROV 200. The TDU chosen typically has a low torque tool mounting bracket 65 fitted to the lower carriage of the ROV 200 and two low torque tools 61, 62 fitted to the port side of the mounting bracket 65. The tools 61 and 62 are primarily for activating isolation valves 31, 32 on the wellhead but can be used for a wide variety of other operations. A grabber tool 63 is fitted to the starboard side of the mounting bracket 65 and holds a single port male hot stab tool 33 fitted with a grabber handle to connect with the grabber tool 63. The male hot stab tool 33 is

typically a standard sampling probe. The male hot stab tool 33 is connected to the sampling equipment 100 by a hose 23 and two hydraulic lines. In practise it may be necessary to alter the configuration of the low torque tools 61, 62 and the grabber tool 63 so they correspond with the receptacles and valves at the particular wellhead where the ROV 200 will be docking.

The TDU has two docking probes 71, 72 which engage receptacles (not shown) at the wellhead. These stabilise the ROV 200 in position when it docks at a wellhead. Alternatively, other docking means may be used.

The sampling skid has a quick-connect fail-safe release mechanism 66 in-line with the hoses 23 to the hot stab tool 33 securely mounted in a suitable location on the ROV 200 frame. The fail safe mechanism is activated when either hydraulic or electric power is lost to the sampling skid and ensures that no hydrocarbons are lost and that the ROV 200 may be recovered. An accumulator 54 is provided, charged with hydraulic power to provide power in sequence to various parts of the skid if necessary. First, the accumulator provides power to the torque tools 61, 62 to close off the isolation valves 31, 32. Then, the fluid connection between the male stab and the female connector is broken. Each of the hoses connecting the male hot stab to the sampling skid are then broken and the male hot stab is left loosely attached to the female member. The hoses which connect the male hot-stab to the skid are self-sealing and so do not pollute the environment when

disconnected. A separate accumulator on the TDU (not shown) provides power for the ROV 200 to disengage from the receptacles. The ROV 200 is then recovered for example by towing in, repaired and re-deployed.

A camera pan unit 68 is provided on the mounting bracket 65 of the TDU positioned to allow the camera to view the low torque tools 61, 62 and the hot stab tool 33. Other tooling cameras (not shown) are provided (i) mounted to the camera pan unit for vertical alignment of the low torque tools 61, 62 and hot-stab tool 33 with their interfaces and to monitor torque tool turns, (ii) mounted to the TDU for horizontal alignment of the low torque tools 61, 62 and the hot-stab tool 33 with their interfaces and to monitor torque tool turns, (iii) positioned to view the pressure gauge 29 and indicator rod 39 on the first sampling bottle 10, (iv) positioned to view the pressure gauge 129 and indicator rod 139 on the second sample bottle 110, (v) positioned to view the status of actuated valves 14, 114, 20, 120, 122. Instead of or in addition to cameras to view the rods and tools directly the condition and positions of the dials and tools can optionally be reported electronically. The monitoring apparatus can be adapted to indicate the characteristics of the sampled fluid on either a continuous or intermittent basis.

Figs. 18a to Figs. 18f show the arrangement of the parts which make up the skid. The sampling apparatus 100 is mounted onto a skid frame 60. Buoyancy members 92 are attached to a buoyancy frame 91 to provide stability to the ROV 200 during operation underwater.

The sampling bottles 10, 110 are connected by a sampling line which comprises a series of valves. A hydraulic supply 52 is provided at the centre of the skid frame 60 to provide a means to actuate the hydraulic valves via a hydraulic circuit. Two compensators 53 are provided to hold the pressure of the oil in the hydraulic circuit above ambient pressure. This ensures that a small leak would not result in water being allowed into the hydraulic circuit. An accumulator 54 provides hydraulic energy to the valve circuit in the event of a power failure. A dedicated interface or control unit 56 receives all cable connections including power connections and control signals such as position indicators, valve and control actuation, and camera signals etc. The control unit 52 is in turn connected to the valve pack 52 which directs hydraulic signals to the valves accordingly. A drawer assembly extends out from each side of the skid frame 60 to access the sampling bottle 10 while onshore. The drawer assembly comprises an outer drawer 64 which houses an inner drawer 63. The outer assembly 64 slides out from the skid and the inner assembly 63 slides out from the outer assembly 64 in a telescopic manner. The sampling bottle 10 is mounted on the inner drawer 63 and may be conveniently accessed. A similar drawer assembly (not shown) is provided for the second sample bottle 110. The gauge typically remains fixed to the sample bottles 10, 110 when removed.

When the samples have been collected from the wellhead the ROV 200 docks at the operating station and a slops

tank 41 is connected to the sampling apparatus 100 by line 123 via a valve 26 and a valve 45 as shown in Fig. 21. The slops tank 41 comprises a tank 42, a pressure gauge 43, a temperature gauge 44 and three valves 45, 46, 47. In practise the first sampling bottle 10 is used to store production fluids that are drawn initially from the collection port at the wellhead, as the initial sample will generally be of fluids that are lodged static in the wellhead rather than an accurate reflection of the fluids flowing through the wellhead. Therefore the fluids from the first sampling bottle 10 will typically be expelled into the slops tank 41.

The pressure 43 and temperature gauges 44 on the slops tank 41 should be visible from manual control valve 26. A blind flange 48 is provided for positive isolation after the inlet piping 49 has been disconnected. Typically the level of the liquid in the tank 42 is measured using a portable, non-intrusive level gauge(not shown).

The sampling apparatus 100 is typically completely vented, dismantled and cleaned between offshore trips. The sampling apparatus 100 is tested prior to each mobilisation to check its integrity and to confirm there has been no degradation of components, such as steels, during storage. The first test is a hydrostatic test. The pressure of the water during the hydrotest will normally be up to 230 barg and de-mineralised water is normally used.

In the hydrostatic test the water pump 25 is connected to the connection means 30 (not as shown) and the valve 12 is opened. Water is pumped into the first sampling bottle until the piston is pushed to approximately half way along the bottle and the valve 12 is closed. The equivalent operation is then performed for the second sampling bottle 110. That is, the water pump 25 is connected to the connection means 130 and the valve 112 is opened. Water is pumped into the second sampling bottle 110 until the piston 116 is pushed to approximately half way along the bottle and the valve 112 is closed. The male plugs 30, 130, 40, 140, 50 are removed to make the system more sensitive to leaks. The valves are then switched to the status as shown in Fig. 1. That is valves 14, 114, 12, 112, 18, 118, 126 are closed off and the remaining valves 11, 111, 13, 113, 17, 117, 19, 119, 120, 20, 22 are opened. De-mineralised water is pumped into the apparatus as shown in Fig. 2. The pressure is increased in steps up to the test pressure of 230 barg.

The water pump is then disconnected and the system left for a period of 30 mins. The pressure is monitored and any change indicates a leak.

Once the pressure test is complete valve 26 can be opened to drain and depressurise the skid. Provided a satisfactory hydrotest has been completed the gas test can now be carried out.

The gas test equipment set-up is shown in Fig 2b. To start the test the skid is depressurised and the valves

12, 18, 112 and 118 are opened to ensure there is no trapped pressure. Hoses are attached to connection points 30, 130. Water will be pushed out through valves 12, 112 when the pistons are pushed to the back of the bottles.

Valves 14, 114, 18, 118 and 26 are closed and valves 11,12,13,17,22,19,20,113,117,119,111,120 and 112 are open as shown in Fig. 2b. The system is then connected to a compressed nitrogen supply via the male/female hot stab connection 33, 34, before the skid 160 is submerged in a water bath and the nitrogen supply regulator is set to 125 barg. Hydraulic pressure is applied to open the hot stab sleeve 35, and the system is then purged with nitrogen. The pistons are checked for movement to ensure that the bottles have been purged. Water should be pushed out the back end of the bottles through the connections at 12 and 112. It is important that the pistons are against their stops at the back of the sample bottle so that the piston seals are subject to a differential pressure.

The hydraulic supply to the male hot stab is then removed in order to close the sleeve 35, and the nitrogen supply is then isolated and disconnected.

The submerged skid 160 is checked for about 30mins for bubbles indicating leaks. If the piston seals are leaking bubbles may be seen leaving the skid from connections in the vents lines from 12 or 112.

With the skid 160 removed from the bath valve 26 is opened and the system is vented to atmospheric pressure.

Before offshore mobilisation the skid can be re-tested in order to check the integrity of all connections. The slops tank 41 is assembled as shown in Fig. 21. Valves 46, 47 are closed and valve 45 is opened.

The slops tank 41 is then filled with nitrogen via the valve 45 up to a pressure of 2.5barg. The outlet ports from all valves are left clear so that leaks past the valves can be detected, and the skid is allowed to stabilise for a period of 10 mins. Valve 45 is closed and the nitrogen supply is disconnected while pressure is monitored for a period of 30 minutes and a soapy solution is applied to all flange joints and valve body joints to check for leaks.

If there is leakage it will most likely be past the valves or from the flanged connection on the vessel. The flanged connections may have to be re-assembled or the valves refurbished/replaced.

After the test the valve on the slops tank 41 can be released and the pressure in the tank allowed to drop until it reaches 0.1 barg.

To transport the skid before operation the sample bottles 10, 110 are filed with a water glycol mix according to the following procedure with reference to

Fig. 3 after the tests for leaks are performed as described already.

The sampling system is vented down to atmospheric pressure. When the leak testing is complete valves 14, 114, 18, 118 and 26 are closed, and all other valves should be open.

A water/glycol supply pump is connected to the connection at 12 and fluid is pumped into the back 27 of the sampling bottle 10, checking that the piston 16 moves towards the front of the bottle.

When the piston 16 reaches the front of bottle 10 valves 12 and 20 are closed, and the water/glycol pump supply line is moved to the connection at 112, so that fluid is pumped into the back of bottle 110. When the piston 116 reaches the front 128 of bottle 110 valve 112 is closed as are valves 120, 22 and 26 in sequence.

At this point the manual needle valves 15, 115 in the vent lines from 14 and 114 should be at ¼ turn open. Pressure caps are then inserted at the exit of valves 26, 12, 18, 112 & 118, and the tubing ends at the vent lines from 14 and 114 are capped off. Valves 26, 12, 18, 112 & 118 are then locked in the closed position, and at this point the bottle pistons 16, 116 should both still be at the front end 28, 128 of the bottles.

The system is now in its transport condition (refer to Fig. 4a). Typically the water/glycol mix will be

present in the sampling bottles when the ROV 100 and attached skid 160 dives.

Spare sample bottles are provided and require to have the production fluid side flushed with de-mineralised water. These bottles should be separately hydrotested to 230 barg and nitrogen tested to 125 barg to test the piston seals and valves.

The back end 27, 127 of each of the bottles 10, 110 is filled with the water/glycol mix so that the piston 16, 116 is at the front 28, 128 of the bottle. All valves on these bottles are left in the CLOSED position (refer to Fig. 4b).

In use for sampling operations, the ROV 200 flies to the wellhead and docks at a panel (not shown). The docking probes 71, 72 are inserted and the ROV 200 is stabilised. The male hot stab 33 on the mounting bracket 65 is aligned with and inserted into the female connection 34 on the wellhead. The grabber tool 63 then releases the hot stab tool 33 and the lower carriage of the tool deployment unit is withdrawn.

Samples are then removed from the wellhead as follows: The current inlet pressure to the manifold flowmeter is checked and recorded with a central processing facility. The pressure can typically be read from the pressure transmitter at the inlet to the flowmeter or from the transmitter within the flowmeter. The operating pressure read at the manifold should not be greater than 97 barg. However, as the accuracy of the

subsea manifold gauges cannot be guaranteed a sample may still be taken even if the manifold gauge reading is greater than 97 barg.

The panel valves should be configured as shown in Fig. 6a. Hydraulic pressure is applied to the male hot stab in order to push back the sleeve 35. The sample isolation valves 31, 32 on the panel are operated using the low torque tools 61, 62. Sample Isolation Valve 32 is opened (Fig. 6b) to admit the sample into the collecting device and then closed. Thus the pressure between the two sample isolation valves 31, 32 will be the flowmeter operating pressure as determined from step 2 (Fig. 6c).

Sample Isolation Valve 31 is opened to expose the hot stab connection to pressure whilst still providing isolation between the flowmeter and the hot stab (Fig. 6d). Preferably the operator should observe that there is no fluid leakage from the hot stab. If there is fluid leakage then Sample Isolation Valve 31 is preferably closed and the sampling operation must be re-attempted after the hot stab connector is checked. In this case the hot stab sleeve 35 is closed and removed while the ROV 200 undocks from the panel and is recovered the surface where the Sample Isolation Valve 32 is opened.

Preferably the XYZ tool position at the Sample Isolation Valves 31, 32 is maintained. This enables quick isolation of the line to be made should any problems be encountered.

Valves 22 and 20 are then opened as shown on Fig. 7. This will expose bottle 10 to the operating pressure. Check that the pressure gauge on bottle 10 indicates the pressure of the sampled fluid, and valve 14 is then opened. This will allow the water/glycol mix to exit from the back 27 of bottle 10 and production fluid into the front 28 (as shown on Fig. 8). The time taken for the piston to move from the front 28 to the back 27 of the sample bottle is recorded. The typical time taken for a 5 litre sample is set out in the table below.

Manifold Pressure (Barg)	Time to take sample (mins)
37	30
50	28
97	22
230	15

The bottle 10 fills with fluid under pressure from the manifold and the fill can confirmed by the piston position indicator. When the piston stops moving the pressure shown on the bottle gauge should increase up to the manifold pressure.

If after 5 minutes the bottle piston has not moved it must be assumed that there is some form of blockage in the line such as a build up of hydrates. In this case the sampling operation may be abandoned. In this case the valves 22, 120 and 31, 32 are closed, and the ROV

200 undocks from the panel and is recovered to the surface.

In the event of satisfactory fill, the valves 20,14 are closed when the piston moves to the back of the bottle.

Valve 120 is opened and the pressure gauge on the bottle 110 is checked to indicate the pressure of the sampled fluid.

Valve 114 is then opened and the time taken for the piston to move from the front 128 to the back 127 of the bottle is recorded. Typically the time to taken for the second bottle 10 to fill will be similar to the times given for the first sampling bottle 10.

As the sampling bottle 110 is filled with fluids from the wellbore at its first end 128, the water/glycol mix is expelled from its second end 127. A throttle (not shown) may be provided to control the rate at which the water/glycol is expelled and so control the rate the sample fluids are introduced into the sample bottle 110. A more representative sample of the fluids in the wellhead is typically recovered in this controlled fashion.

When the bottle is full the piston rod 139 will be fully extended and the pressure shown 129 on the bottle gauge will increase to the manifold pressure.

Valves 120, 114, 31, 32 and 22 are closed in that sequence and hydraulic pressure is removed from the

male hot stab 33 in order to close the sleeve 35. The hot stab 33 is removed from the female connector 34.

The docking probes can be released and the ROV 200 may undock the from panel. The sampling equipment should now be configured as shown in Fig. 9.

The ROV 200 is then brought back to the rig or other operating station where the sampled fluid is recovered.

The actual arrangement of equipment can vary according to the ROV 200 and other factors. Gravity is sometimes required to assist the flow of fluids from the sampling skid to the slops tank and the arrangement of the equipment on the vessel can optionally take account of this. Typically the slops tank should be located on the deck of the vessel such that the flexible vent line from the safety relief valve can extend over the edge of the vessel. The end of the flexible should preferably be situated such that it is not adjacent to any intakes, exhausts or ignition sources. The vent line should typically be secured to the side of the vessel and the area around the line roped off to personnel. The weather conditions at the time of the sampling operation should also be taken into account. This may necessitate re-locating the vent hose end.

If possible the ROV 200 launch/recovery platform should be located at a higher elevation than the top of the slops tank 41. This is to allow the waste fluids from the skid to flow into the slops tank 41.

The slops tank 41 should be positioned during transport such that it is within reach of one of the vessel cranes. This is so that, if necessary, the sampling skid can be lifted above the slops tank 41. This may be required to give the necessary height above the slops tank 41 if this cannot be achieved from the ROV 200 launch/recovery station.

The slops tank 41 should be located sufficiently close to the ROV 200 launch/recovery station such that the hose used for venting operations can reach between the connection points at 26 on the skid and the valve (not shown) on the slops tank 41.

After recovery to the surface the bottle containing the production sample is removed from the skid. The replacement of sample bottles will generally be carried out with the skid on the deck. To this end each sampling bottle 10, 110 is mounted on a drawer assembly 63, 64 and can be conveniently accessed. It is suggested that the connections to the ROV 200 are maintained so that hydraulic power is available to operate the actuated valves. However, if the ROV 200 is urgently required for other tasks then the skid can be disconnected from the ROV 200 and the manual overrides on the actuated valves used. This can be achieved using a hydraulic hand pump via a manual switching circuit on the skid or by a screw to maintain the piston on the valves in a closed position, so that individual valves can be physically closed. All actuated valves will typically fail in the closed position when the hydraulic supply is removed. The

hot-stab comprises a spring return mechanism which will activate when the cylinder has been vented and so does not require hydraulic power to in order to open it.

The pressure shown on the bottle gauges is checked. If either bottle contains fluid at greater than 97 barg then this is outwith normal operating conditions and the bottles cannot be vented as detailed below. This is due to the excessively low temperatures that would be produced when venting fluids of this pressure to the slops tank 41. These abnormal pressures are likely to be as the result of a process upset and further sampling should not be carried out until the cause of this upset is determined. If the sampling operation is to be continued then the two bottles containing the high pressure production fluids will have to be removed and new bottles inserted as will be described later.

As bottle 10 will be used for each sampling it must be vented and re-filled with water/glycol between each run. Venting the skid makes use of the slops tank 41. The following checks should be made each time the slops tank 41 is used:-

Valves 45, 46 and 47 should be closed. This is particularly important the first time the tank is used offshore as it will have been filled and purged with nitrogen before shipping. If valves 46 or 47 are found to be open then the slops tank 41 must be re-purged before use. Pressure in the tank should not be greater than 2.0 barg prior to each filling operation.

Temperature of the tank should be in the range -6°C to +50°C.

The tank level indication on the ultrasonic level detector is then checked. Level of the fluid in the tank should be 200mm or less. The vent piping from the pressure safety valve should be attached and discharged to a safe area. The end of the vent piping should be free from blockages. The hose used to connect to the sampling skid should be in good condition and the end connection should be checked for debris.

In order for the production fluids to be drained from the skid should typically be at a higher elevation than the slops tank 41. If the ROV 200 launch platform is located above the top of the slops tank 41 level then the skid should be kept on the ROV 200 and the hydraulic supply can be used to actuate the valves. Ideally the operator at the ROV 200 location should be able to view the pressure and the temperature gauges on the slops tank 41 while valve 26 on the skid is being operated. If this is not possible the operator at the skid should preferably have a clear view to the slops tank 41 and a second operator should be stationed at the slops tank 41 to monitor the gauges.

If the ROV 200 launch/recovery station is not at a higher elevation than the top of the slops tank 41 then the skid may have to be removed from the ROV 200 and lifted above the slops tank 41. The following steps must be taken:-

1. Close all valves on the skid.
2. Vent down all the hydraulic connections to the skid (actuated valves and hot stab).
3. Disconnect all hydraulic and electrical lines from the ROV 200.
4. Remove the skid from the ROV 200.
5. The skid can now be moved by its lifting points to a location at a higher elevation than the slops tank 41.

The manual overrides on the hydraulic valves will now have to be used to operate them. The operator should be able to view the pressure 43 and temperature 44 gauges on the tank while valve 26 is being operated. If the ROV 200 launch/recovery station is at a higher elevation then these steps are not necessary. Regardless of the position of the ROV 200 launch/recovery station, the following steps should be taken.

Valves 111, 113, 117 and 119 should be closed and valves 11, 13, 17 and 19 should be opened.

Valve 26 should be closed, and any pressure released from behind the plug at 26 before it is removed. The plug 50 is then backed off and the cap is depressed to vent any trapped pressure. Once the plug 50 is removed the hose is connected from the connection at valve 26 to the slops tank 41. Valve 45 on the slops tank 41 is then opened, as is valve 26 (slowly) until fluid is heard to escape through the valve to the slops tank 41 (the valve will have to be unlocked first). The valve

will reach extremely low temperatures while the fluid vents through it. The pressure and temperature in the slops tank 41 should be monitored at all times when 26 is open. The slops tank 41 pressure should be kept below 2.5 barg. If the temperature falls below -25°C then valve 26 should be closed, and the temperature allowed to return to above -25°C before valve 26 is opened again.

Valve 22 is opened, then 120, then 20; this will vent the contents of bottle 10 to the slops tank 41. The system will then be configured as shown in Fig. 10. The pressure and temperature in the slops tank 41 is then monitored recorded and maintained within limits stated above.

Valve 14 is opened and the water/glycol supply pump is connected to the connection point at 30. Valves 22 and 120 are then closed.

Valve 12 is then opened and water/glycol is pumped into the back of bottle 10, checking that the piston 16 moves towards the front of the bottle 28. Production fluid will be expelled through the connection at valve 26 into the slops tank 41 as shown in Fig. 11.

When the piston 16 reaches the front of bottle 10 valve 12 is closed. Valves 26 on the sampling skid and 45 on the slops tank 41 are then closed.

At this point, the bottle 10 has been vented but the section of pipework between valves 119 and 114, including bottle 110, is still at pressure.

The bottle 110 should now be removed. Before bottle 110 can be removed the pressure either side of the bottle must be vented, by closing valves 113 and 117, backing off the plugs 130 and 140 and then depressing the cap to release any trapped pressure before removing the plugs. Valve 120 is closed, and the slops tank 41 hose is connected to the connection point 140.

Valves 45, 119 and 118 are opened sequentially to vent the section of pipe between valves 117 and 20. There should only be a small release of fluid from this small section of pipe. If there is continual fluid release and the pressure in the bottle falls then this indicates valve 117 is passing. Valves 118 and 119 should in that case be closed, and the bottle can only be removed if it is first completely vented to the slops tank 41.

Valves 45, 118 and 119 are closed sequentially, and the hose to the slops tank 41 is disconnected from valve 118.

The fluid at the back end of bottle 110 will be at the hydrostatic water head pressure when the sample was taken (around 10 barg for 100m depth). This pressure must be vented before the bottle can be removed.

The slops tank 41 hose is connected to the connection 130, and the valves 45 and 112 are opened. The bottle is still isolated by valve 113. If the pressure in the bottle falls when valve 112 is opened then this indicates both the bottle piston seals and valve 113 are passing. In this case the bottle must be completely vented to the slops tank 41 before it can be removed. This should be done through valves 117 and 118.

Valves 111 and 114 are opened, and valve 45 on the slops tank 41 is closed before the hose 51 to the slops tank 41 is disconnected. Valves 111, 112, 118 and 119 are closed (Valves 113 and 117 should already be closed).

Valves 120 and 26 are then opened to ensure both the points where the bottle connects to the skid are open to atmospheric pressure. Bottle 110 still contains production fluids at pressure and so should be handled with care. Bottle 110 is disconnected.

A new bottle to be inserted should be pre-filled with the water glycol mix at the back of the sample bottle. The double block and bleed valves either side of the bottle should be closed. The piston should be at the front of the bottle and the pressure gauge should read zero. The new sampling bottle should then be fitted to the skid, checking that valve 119 connects to 120 and 111 connects to 114.

The pipework between the hot stab and the sampling bottles will have to be flushed through to prevent

contamination between samples. De-mineralised water is preferably used for the flushing operation in order to avoid contamination of samples.

The skid valves should be configured as below:-

Closed Valves		Open Valves
11	22	17
12	120	19
13	20	117
18	26	118
111	14	119
112	114	
113		

There are three legs of pipework on the skid that must be flushed through. The hot stab and check valve must be disconnected and flushed in the flow direction due to the presence of the check valve. Thus there are four sections to be flushed; labelled A, B, C and D on Fig. 14.

The de-mineralised water pump is connected to the connection point 140 as shown in Fig. 14, and a hose from the connection at valve 26 is connected to a suitable receptacle. Valves 26 and 120 are opened and the system should now be configured as shown in Fig. 14. De-mineralised water is then pumped through the pipework, and fluid will exit from the hose at 26 to be collected in the receptacle. Pumping is continued until the fluid exiting 26 is clean, at which point

valve 26 is closed, valve 20 is opened, and the hose is moved from 26 to 40. Valve 18 is then opened and de-mineralised water is pumped through the pipework, with fluid draining from 18 and pumping continuing until the fluid exiting is clean. At that point, valves 18 and 20 are closed and valve 22 is opened, the hot stab and check valve are disconnected from the rest of the skid at the QC coupling.

The hose is transferred from 30 to the QC coupling, and de-mineralised water is pumped through the pipework, draining through the hose at 22, until clean, whereupon the water pump is disconnected from the skid, the hot stab is inserted into the dummy female receptacle, the water pump is connected to the connection on the female stab 34, the hot stab sleeve 35 is opened by hydraulic pressure and de-mineralised water is pumped through the hot stab and check valve, until clean.

The water pump is then disconnected from the female stab 34, and valves 22 and 26 are closed.

The skid pipework is then purged with nitrogen prior to each sampling run. This will be done to remove air from the pipework prior to the introduction of hydrocarbons.

The nitrogen supply is connected to the connection point 140 as shown in Fig. 15. Valves 26 and 120 are opened and the system should now be configured as shown in Fig. 15.

The nitrogen supply is opened and the system is purged through for a few seconds. Fluids will exit from the connection at 26.

Valve 26 is then closed, and valves 20 and 18 are opened. After a further nitrogen purge for a few seconds fluids will exit from the connection at 18.

Valves 18 and 20 are closed, and valve 22 is opened.

After a further nitrogen purge, fluids will exit from the end of the hose where the check valve and stab are normally attached.

Valves 22 and 118 are closed and the nitrogen supply is disconnected from the skid and connected to the connection on the female stab 34.

The hot stab sleeve 35 is opened by hydraulic pressure, purged with nitrogen for a few seconds and closed before the check valve and stab are re-connected to the skid pipework.

Hydraulic pressure is then applied to open the hot stab sleeve 35, and checking that valves 18, 118 and 26 are closed, valves 22, 120 and 20 are opened. The system should be configured as shown in Fig. 16.

A nitrogen purge is generally conducted in two steps to achieve a nitrogen purity of 99.9% of volume in the skid pipework. Typically the piping is filled with

nitrogen to a pressure of 15 barg, and the nitrogen supply is isolated.

Valve 26 is opened to vent the nitrogen, and then closed.

The nitrogen supply is then opened and nitrogen fills the piping to a pressure of 15 barg, after which the nitrogen supply is isolated and the pipes are vented by opening and closing valve 26.

As the connections between bottle 110 and the rest of the pipework have been broken they must be re-tested before another sample can be taken as follows: the nitrogen supply is connected to the connection point at valve 118 and the nitrogen supply regulator is set to 125 barg. At this point the bottle piston 116 should be at the front 128 of bottle 110 and the bottle and piping behind the piston 116 should be filled with the water/glycol mix.

The skid valves should be configured as follows and as shown in Fig. 17.

Closed Valves	Open Valves
114	111
14	113
11	117
12	118
13	119
18	17

112	19
22	
120	
20	
26	

The above configuration will allow the piping between valve 120 and the sampling bottle piston 116 to be filled with nitrogen. The pressure in the pipework is shown on the bottle pressure gauge. As the piston 116 is free to move, the water/glycol mix at the back of the bottle will also be pressurised from the bottle piston 116 through to valve 114. Thus both of the points where the bottle is connected into the skid will be tested. The bottle piston seal need not be tested, as this will have been done onshore. Only a small volume of nitrogen will be required to test the piping. Thus the pressure in the piping will rise quickly when the nitrogen supply is opened.

Soapy water is applied around the bottle connection point adjacent to valve 20 to detect leaks. The connection at the rear of the bottle should be dried.

The nitrogen pressure is gradually increased to a pressure of 125 barg. The bottle piston 116 should not move a significant amount during the test. If the piston continues to move during pressurising then this indicates a leak from the piping at the back end of the bottle.

The nitrogen supply is closed by valve 118 and disconnected, and the system is left pressurised for 30 minutes. Assuming no leaks valve 118 is opened to vent off the nitrogen.

Once all sampling operations are complete the sampling skid can be disconnected from the ROV 200. The skid itself should not contain any fluids at pressure. The only fluids at pressure will be within the sample bottles.

The hydraulic supply lines to the sampling skid valves are vented to atmospheric pressure, disconnected and stored in the transportation case.

All electrical supply and control cables are disconnected between the ROV 200 and the skid, any hydraulic or electrical ports on the skid are capped to prevent debris ingress. All valves are closed and pressure caps are fitted on the outlets of valves 26, 12, 18, 112, 118. The flexible pipe from the safety relief valve on the slops tank 41 should be checked for security and left in place until the slops tank 41 is demobilised from the vessel.

Before storage the valves 46 and 47 should be closed and valve opened The outlet ports from all valves should be left clear so that leaks past the valves can be detected. A final leak test is then carried out by filling the tank with nitrogen through the connection point at valve 45 to a test pressure of 2.5 barg for 10 minutes, after which the valve 45 is closed and the

nitrogen supply is disconnected. The pressure and temperature are monitored over a period of 30 minutes, and a soapy solution is applied to all flange joints and valve body joints to check for leaks. If there is leakage it will most likely be past the valves or from the flanged connection on the vessel. The flanged connections may have to be re-assembled or the valves refurbished/replaced.

The nitrogen can be vented by opening valve 46. A slight positive pressure of 0.1 barg is preferably maintained within the vessel.

Modifications and improvements can be incorporated without departing from the scope of the invention.

Claims

1 A method for sampling a fluid produced from a wellbore, the method comprising providing a vehicle having a drive means for moving the vehicle, a collecting device for collecting a sample of fluid and a storage facility for the collected fluid; using the collecting device to recover a sample of the fluid to the vehicle's storage facility at a first location on a subsea structure; storing the sample in the storage facility of the vehicle; and carrying the sample in the vehicle's storage facility to a second location.

2 A method as claimed in claim 1, wherein the first location is a wellhead.

3 A method as claimed in claim 1, wherein the first position typically has a collection port to mate with the collecting device, and the method includes the step of engaging the collecting device with the collection port at the first location, and transferring the fluid through the collection port and collecting device while they are engaged.

4 A method as claimed in claim 1, wherein the vehicle is a remotely operated vehicle.

5 A method as claimed in claim 1 wherein the storage tank and collecting device are housed on a frame attached to the vehicle.

6 A method as claimed in claim 1, wherein the collecting device comprises at least one sample container for containing the sample collected, and the method includes the further step of storing the sample collected in the sample container.

7 A method as claimed in claim 1, wherein the vehicle has a probe for connecting to the subsea structure at the first position and the method includes the step of connecting the vehicle to the subsea structure via the probe and collecting the sample through the probe.

8 A method as claimed in claim 1 including the step of discarding a portion of the fluid collected.

9 A method as claimed in claim 1 including the step of detaching the vehicle from the subsea structure at the first position, removing the sample when the vehicle has moved to the second position, and analysing the sample at the second position.

10 A method as claimed in claim 1, wherein the collecting device has several separate sample containers for collecting samples, and the method includes the step of collecting a further sample from at least one other subsea structure before the vehicle moves to the second location for analysis of the samples.

11 A method as claimed in claim 1, wherein the device can be controlled from a position remote from the first

position, and the method includes the step of controlling the device remotely.

12 A sampling device for collecting samples of fluid produced from a subsea wellbore, the sampling device having a drive means for moving the sampling device, a collecting device for collecting a sample of fluid and a storage container for holding the collected fluid.

13 A sampling device as claimed in claim 12, wherein the wellbore has a wellhead and the collecting device comprises a probe for engaging a port on the wellhead.

14 A sampling device as claimed in claim 12 wherein the drive means comprises a remotely operated vehicle.

15 A sampling device as claimed in claim 12, wherein the storage container comprises at least one bottle, the said at least one bottle having a having a piston movable within the bottle.

16 A sampling device as claimed in claim 12, having means to indicate characteristics of the sample collected, the characteristics being selected from the group consisting of pressure, volume and temperature.

17 A sampling device as claimed in claim 12, wherein the device is adapted to collect the fluid sample from a subsea fluid-carrying structure selected from the group consisting of wellheads, manifolds, pipelines, wellbores, casings, tubulars, storage tanks and gravity base structures.

18. A sampling device as claimed in claim 16, wherein the indicator means is configured to indicate the selected characteristics on a continuous basis.

19. A sampling device as claimed in claim 12, wherein the storage container has a fail safe valve to seal the container in the event of a power failure.

Abstract

A method and apparatus for sampling fluids from an undersea wellbore comprising a self-propelled underwater vehicle and a collection and storage device; so that samples may be recovered directly from the wellbore and subsequently analysed to determine the characteristics of the oil produced from separate wells.

6. SKETCH OF SAMPLING EQUIPMENT

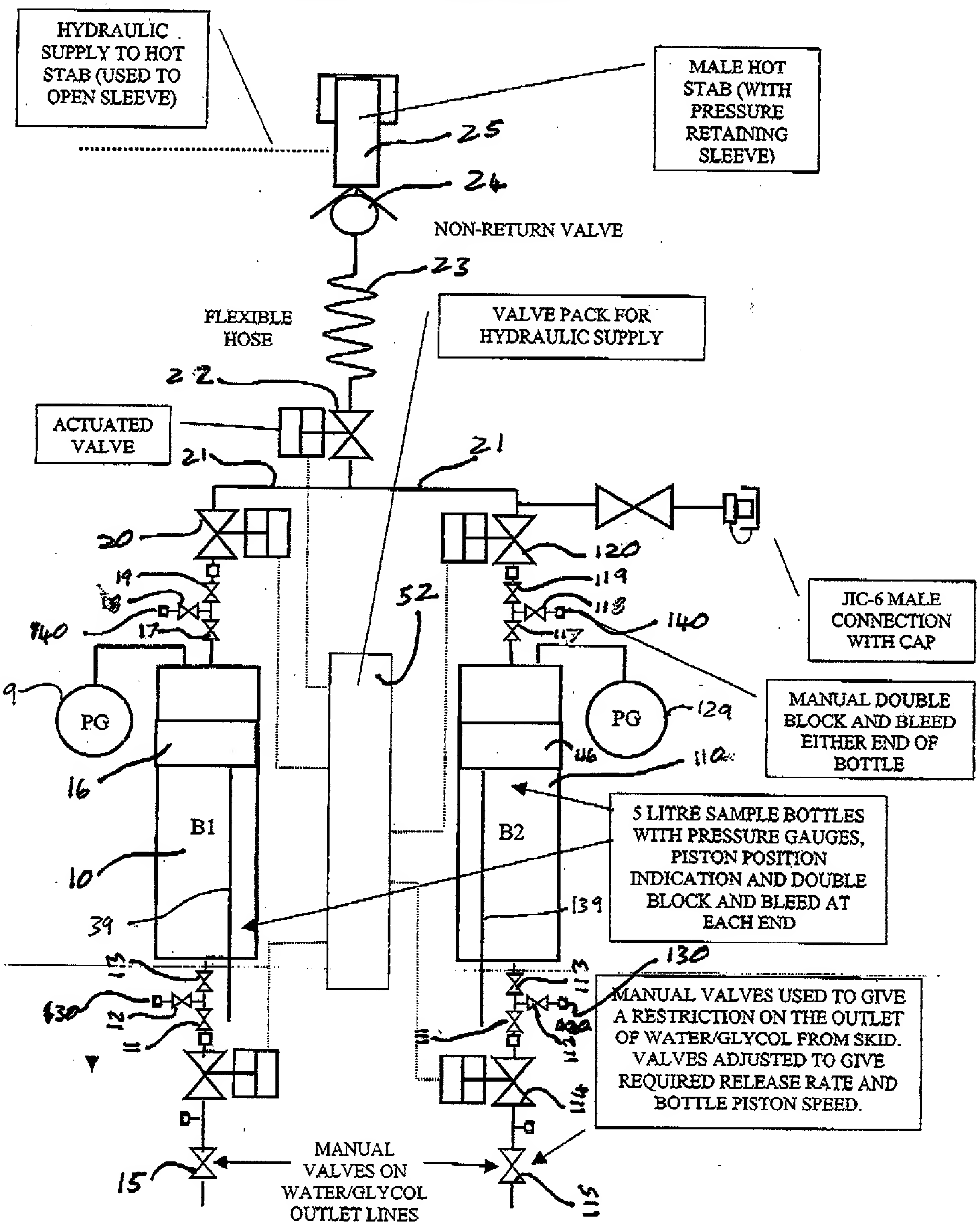

Figure 1

Sketch 1 – Onshore Hydrotest

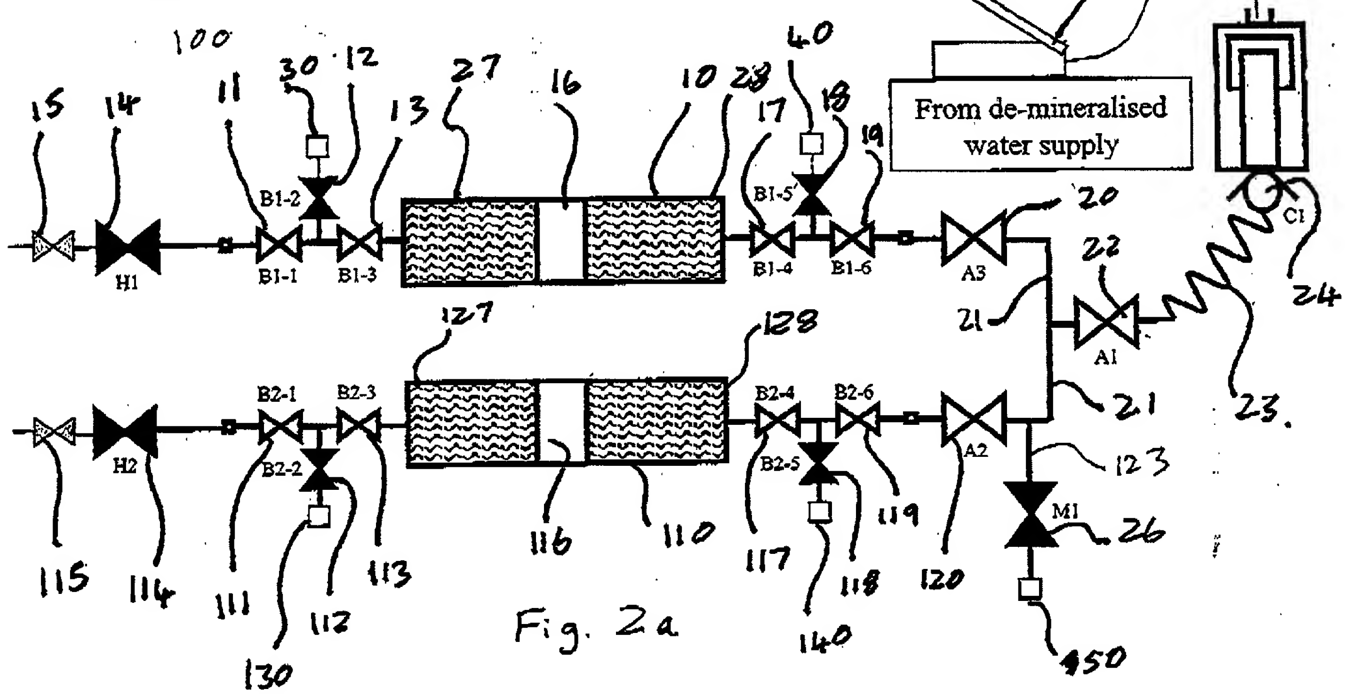

Fig. 2a

Sketch 1 a – Nitrogen Leak Test

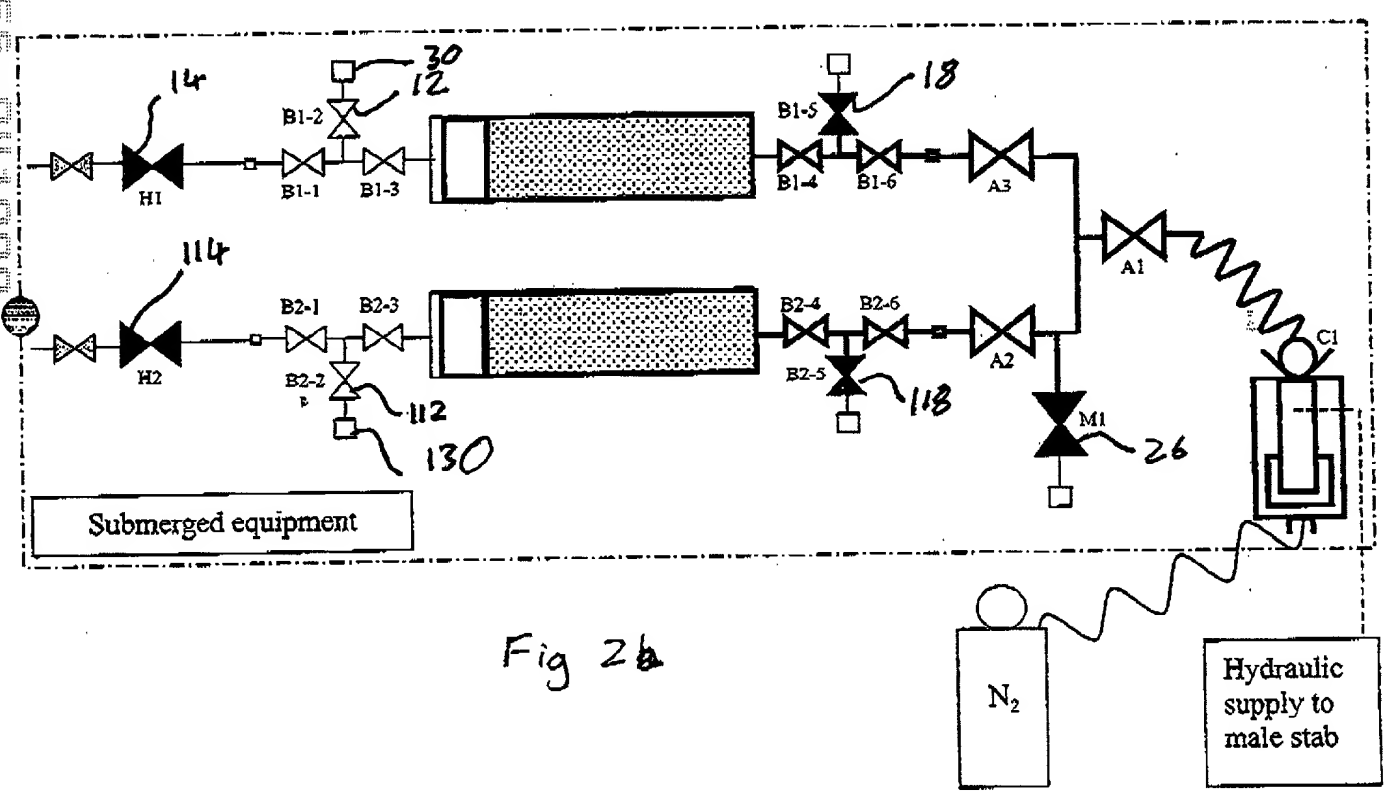

Fig 2b

Sketch 2 – Bottle Fill and System Purge

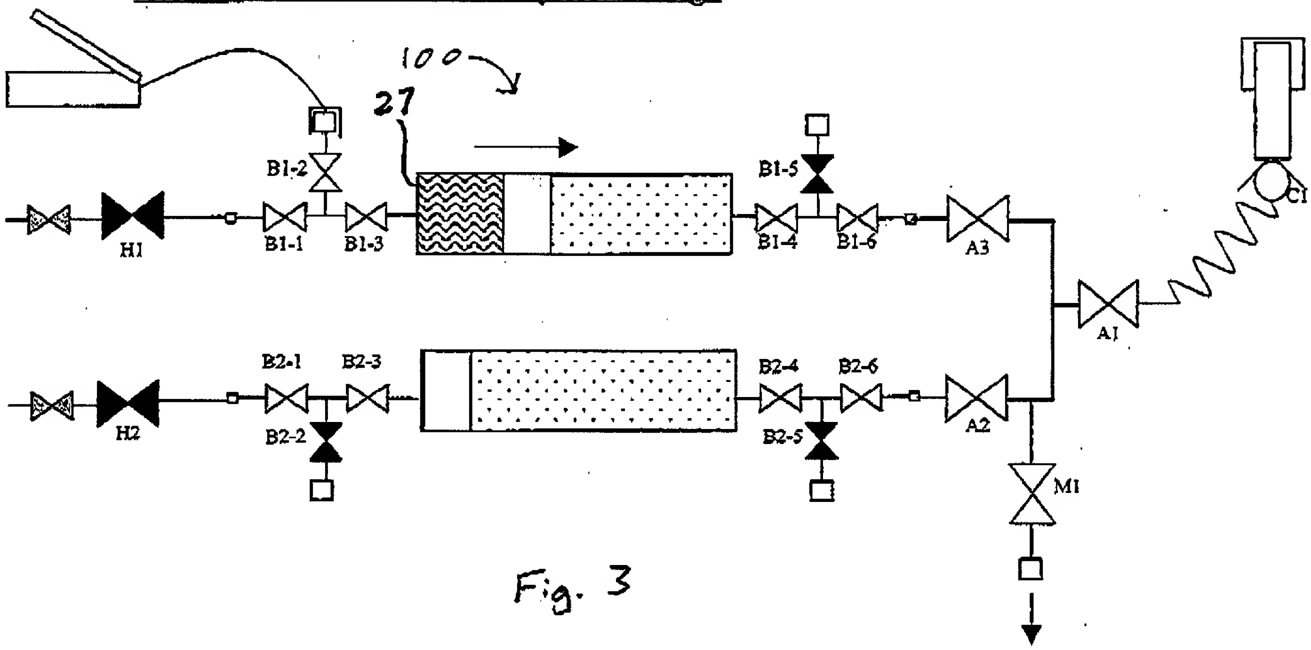

Fig. 3

Sketch 3 – System Transport Condition

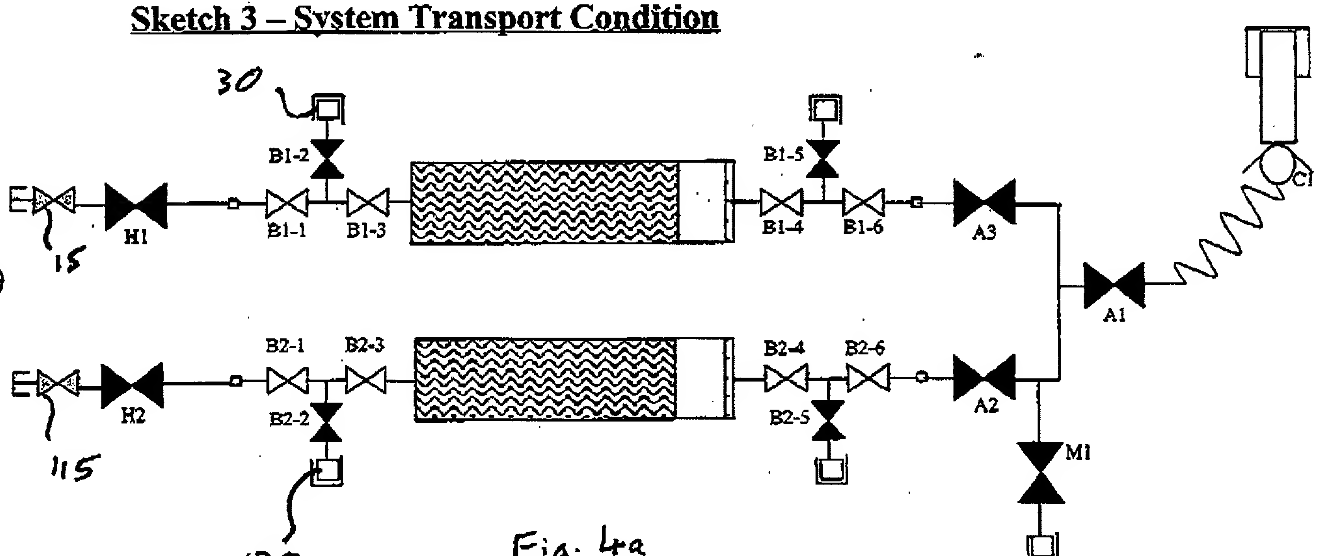

Fig. 4a

Sketch 3 a – Spare Sample Bottle Transport Condition

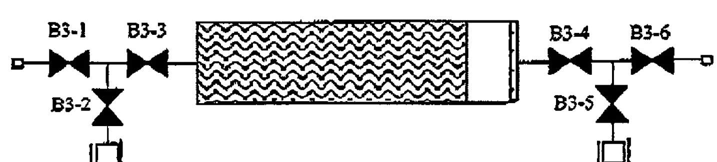

Fig. 4ab

Sketch 4 – Prior to Dive

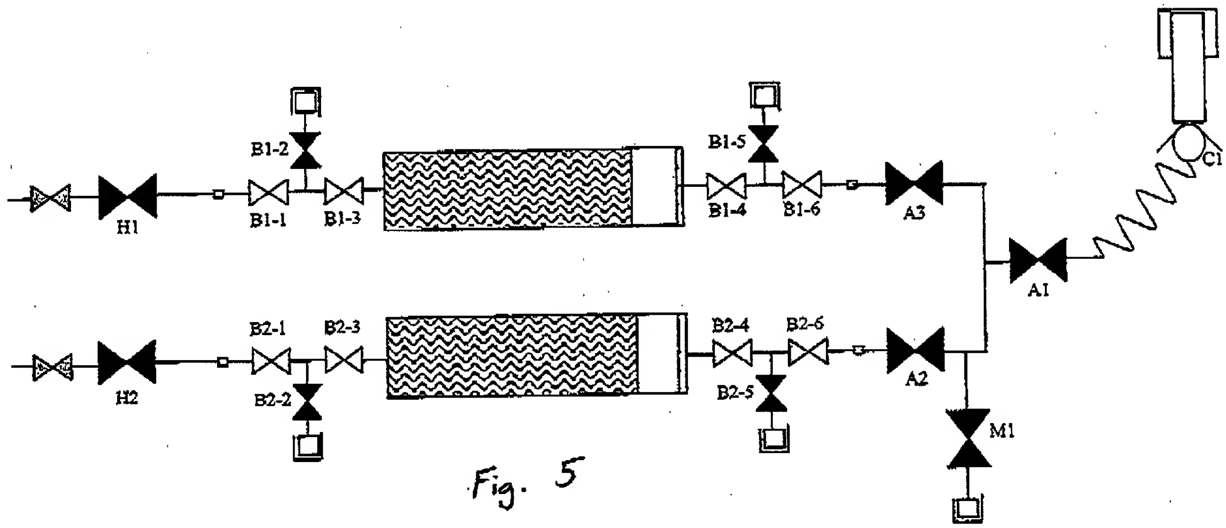

Fig. 5

Sketch 5 – After ROV Docked at Panel

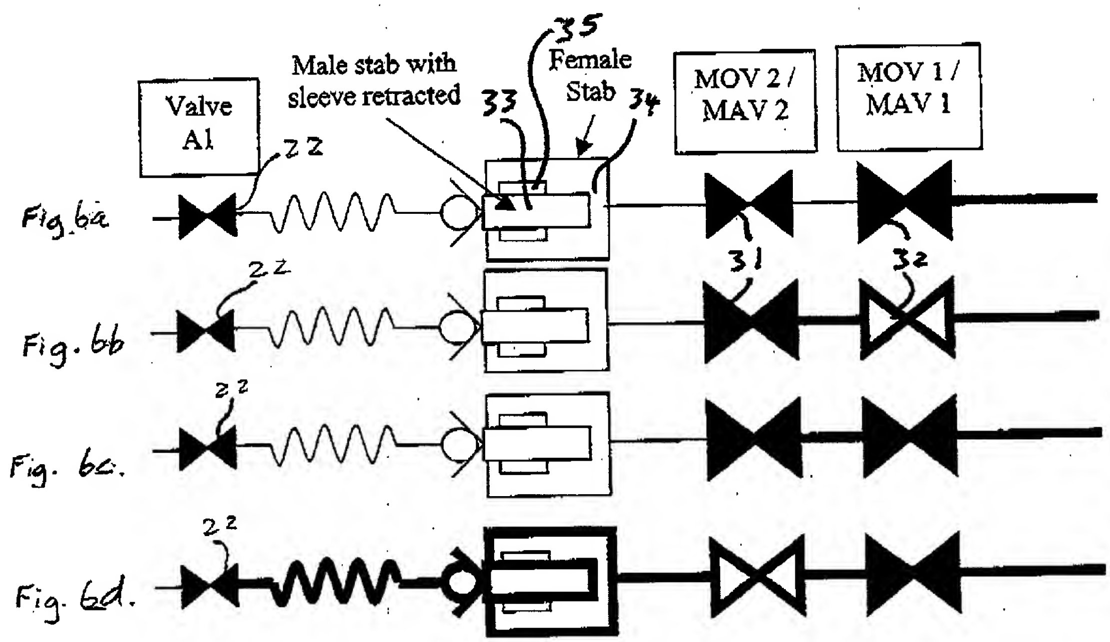

Fig 6a–d

Sketch 6 – Start of Sampling Operation

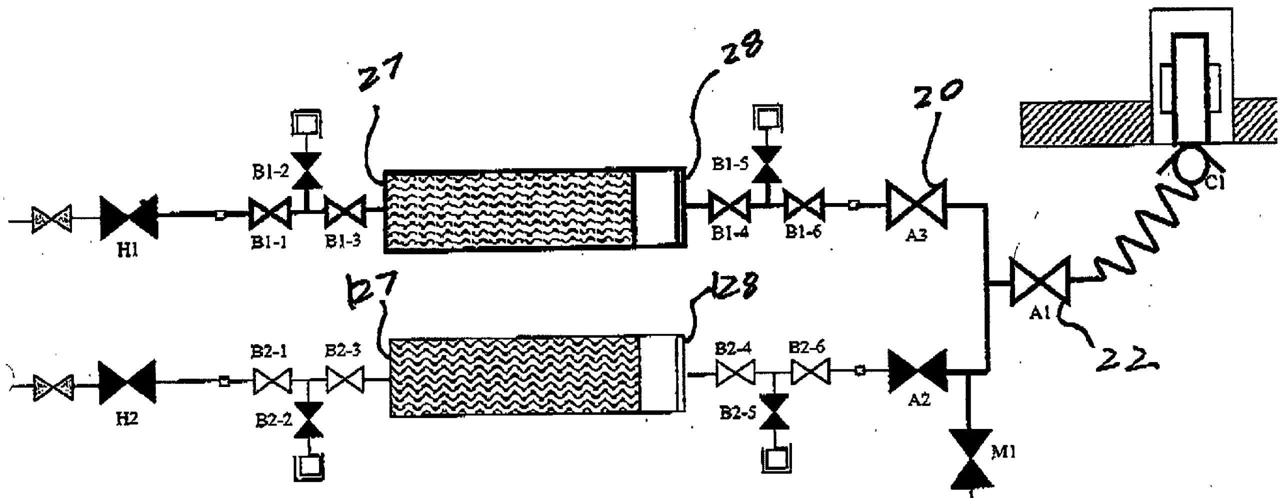

Fig. 7

Sketch 7 – Sampling Into Bottle B1

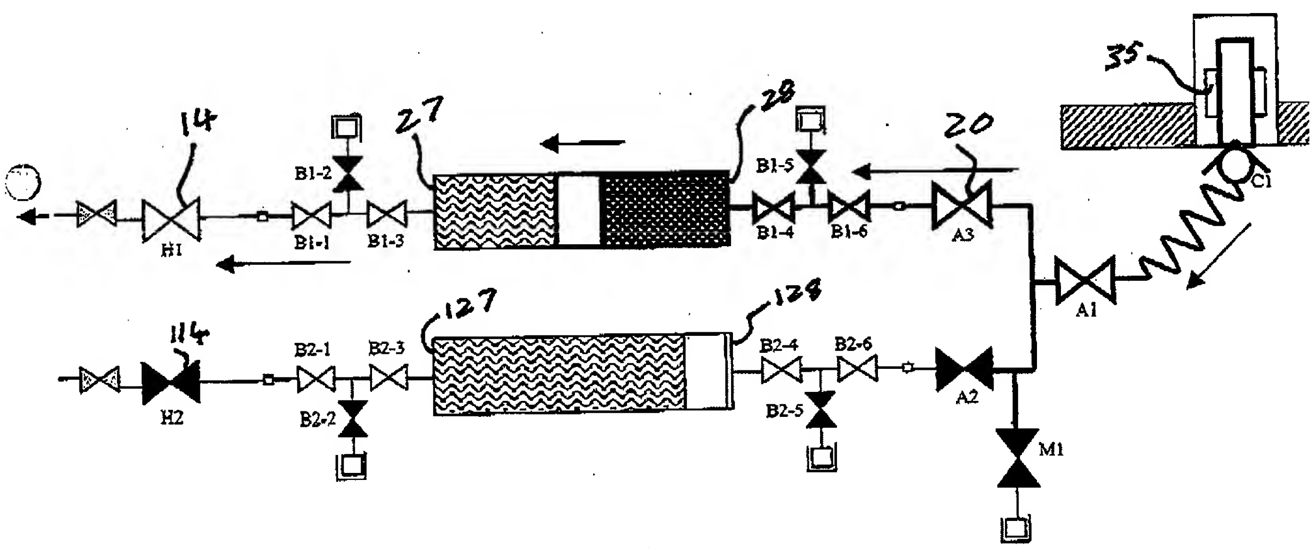

Fig. 8

Sketch 8 – Sampling Complete, Recovered to Surface

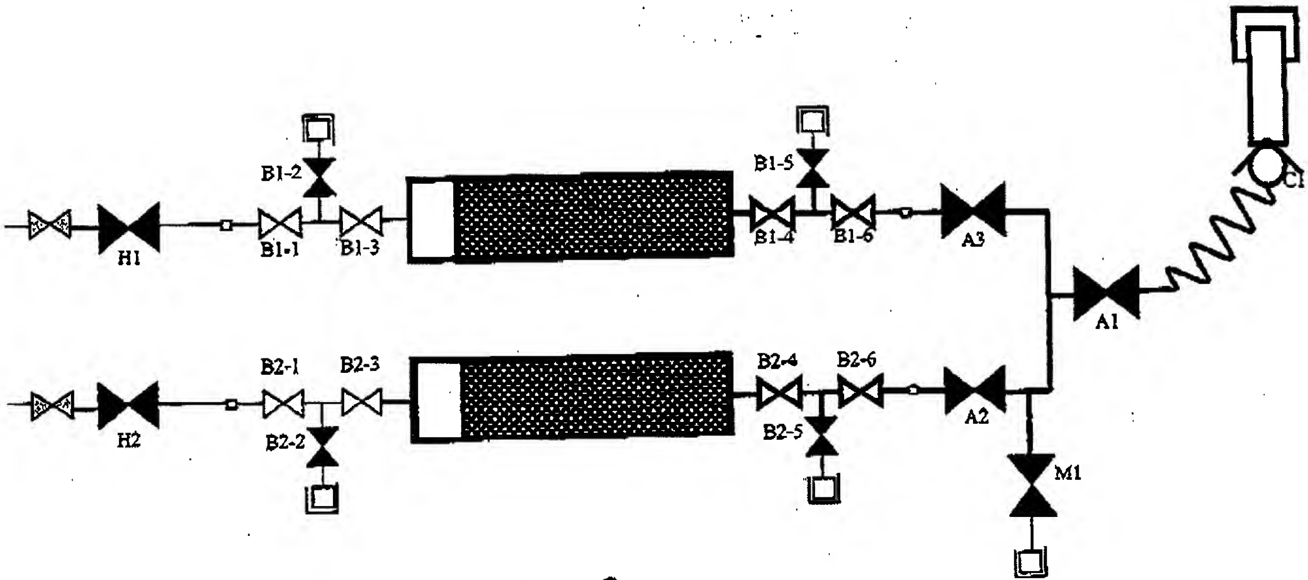

Fig. 9

Sketch 9 – Venting of Bottle B1 to Slop Tank

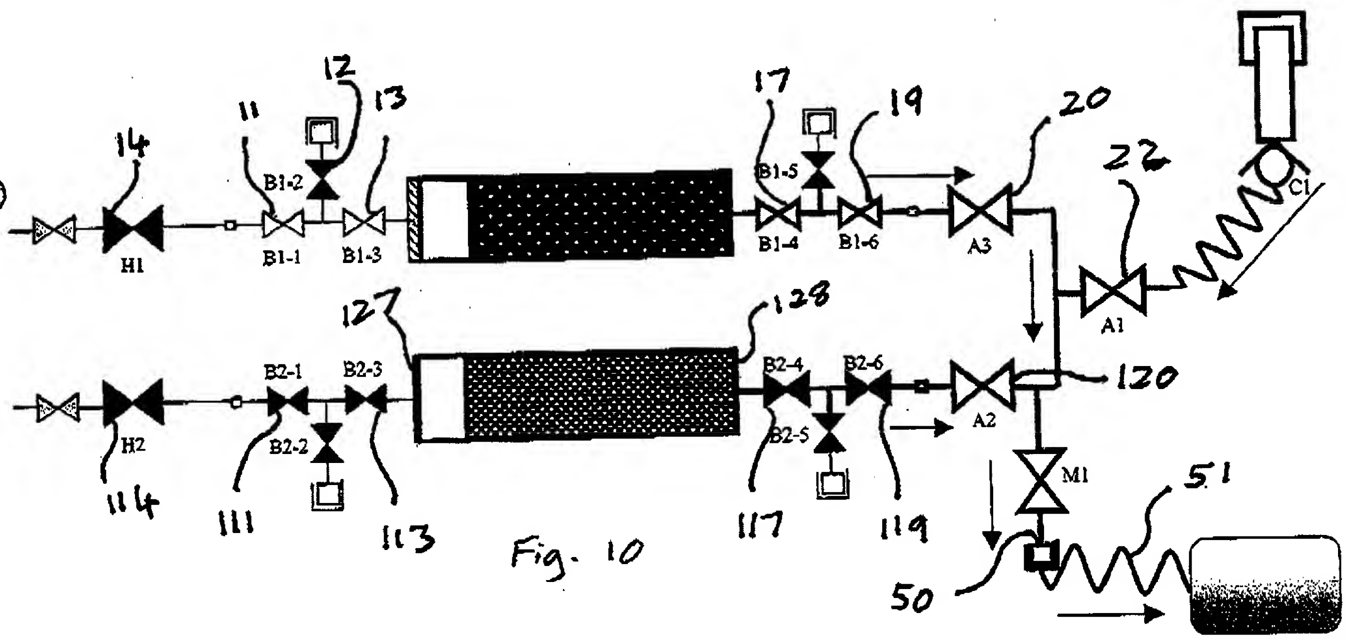

Fig. 10

Sketch 1 – Filling Back of Bottle B1 with Water/Glycol

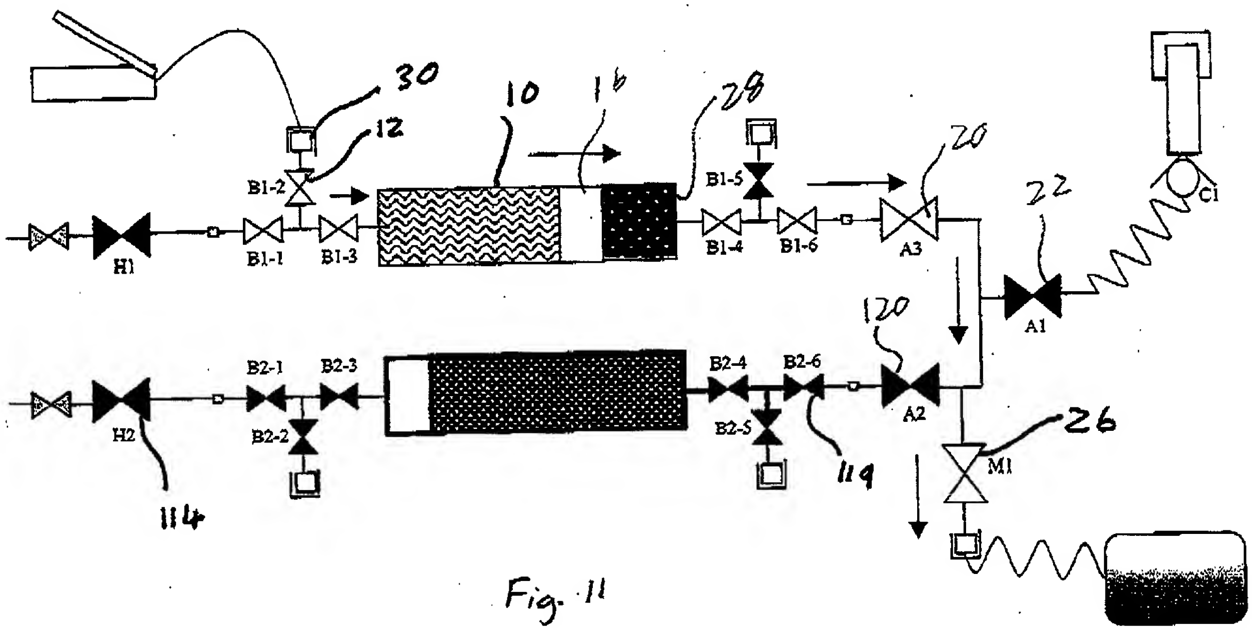

Fig. 11

Sketch 1 – Venting Pipework Either Side of Bottle B2 Prior to Removal

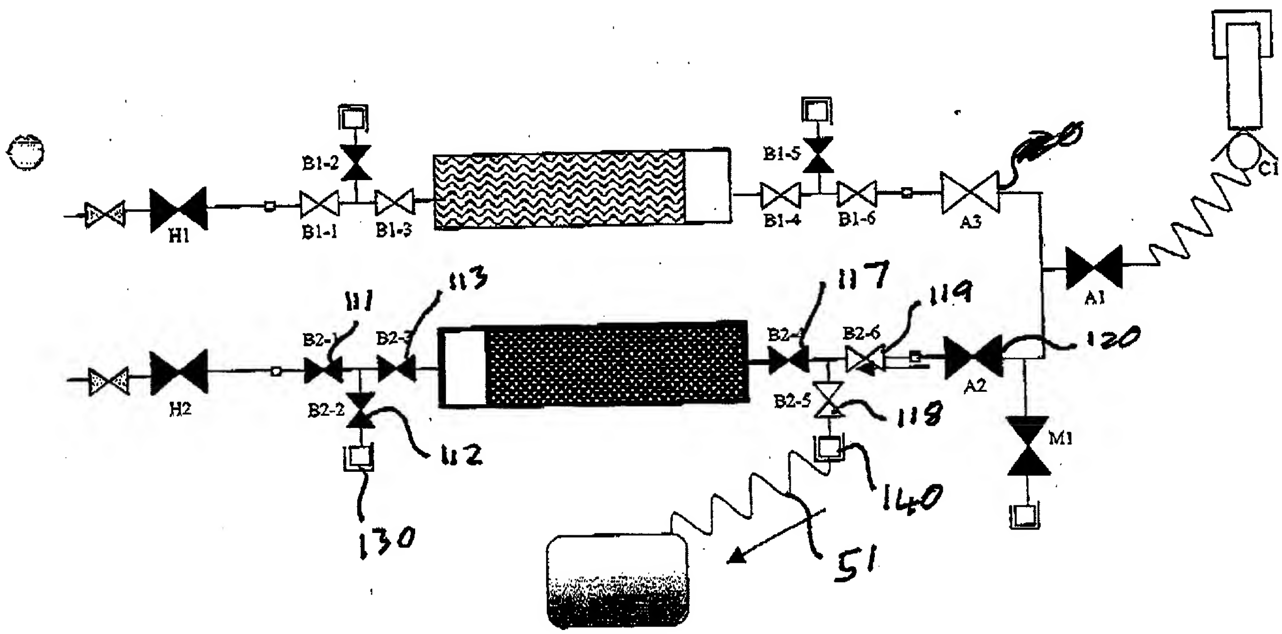

Fig. 12.

Sketch 1 – Removal of Bottle B2

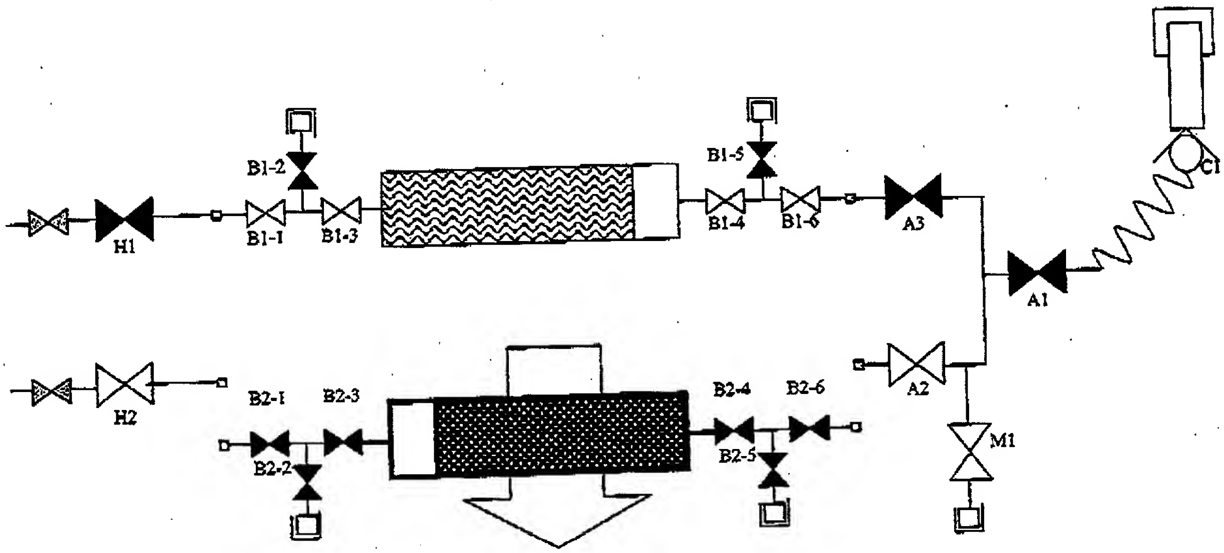

Fig. 13

Sketch 1 - New Sample Bottle Fitted, Flushing of Pipework

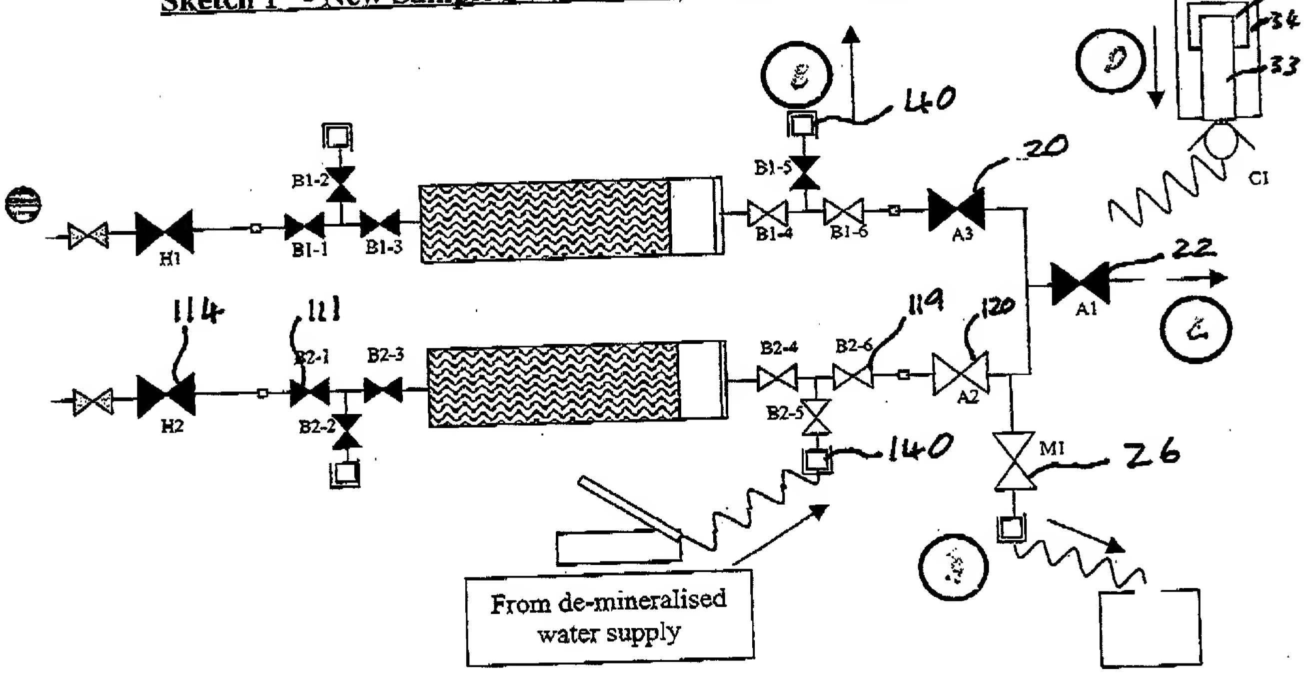

Fig. 14

Sketch 1 – Purging of Pipework with Nitrogen

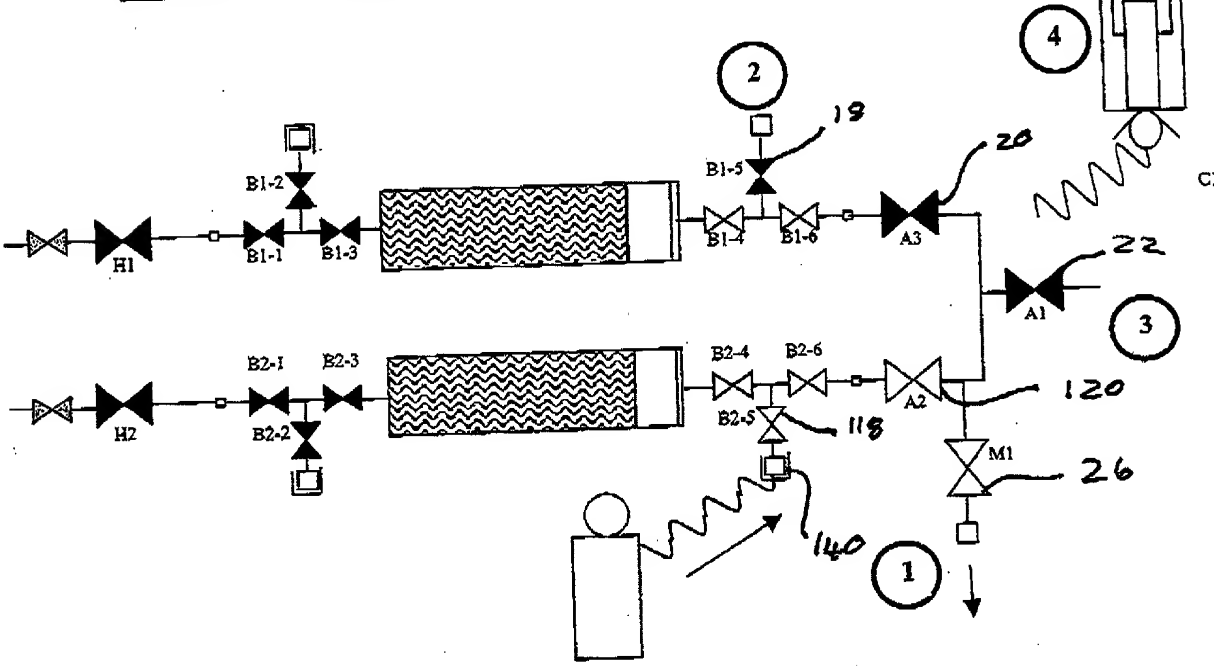

Fig 15

Sketch 1 –Nitrogen Fill of Skid

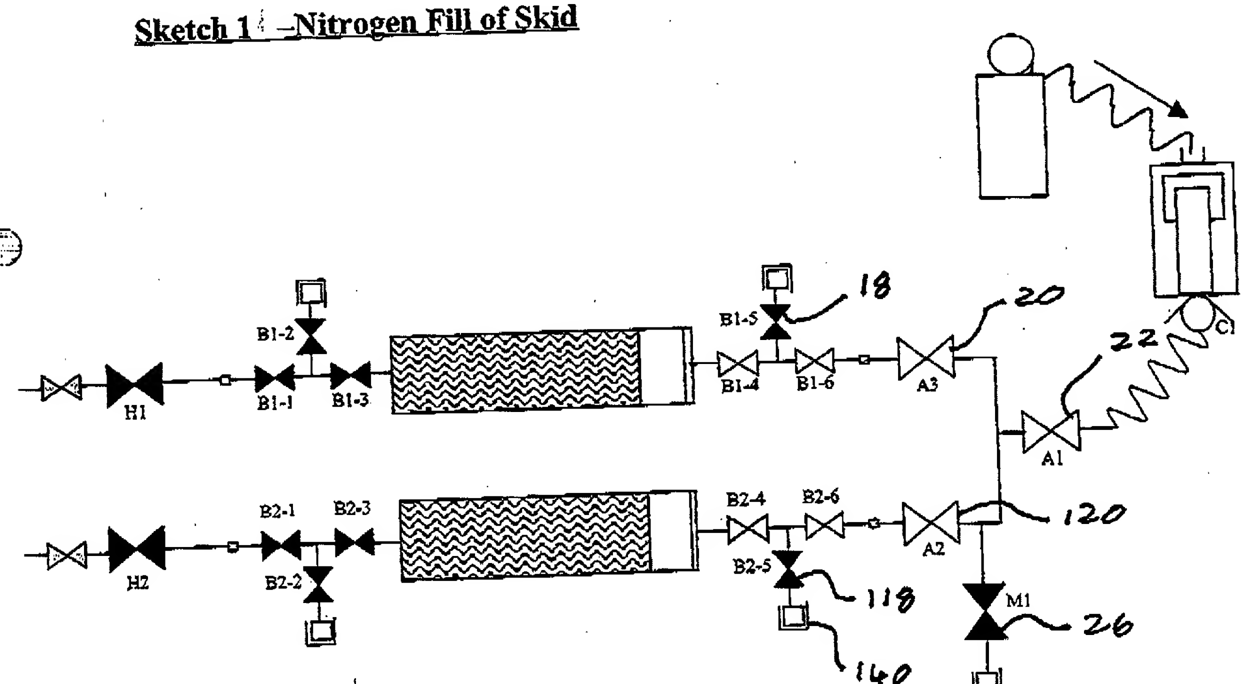

Fig. 16

Sketch 1 – Leak Test of Bottle Connection Points

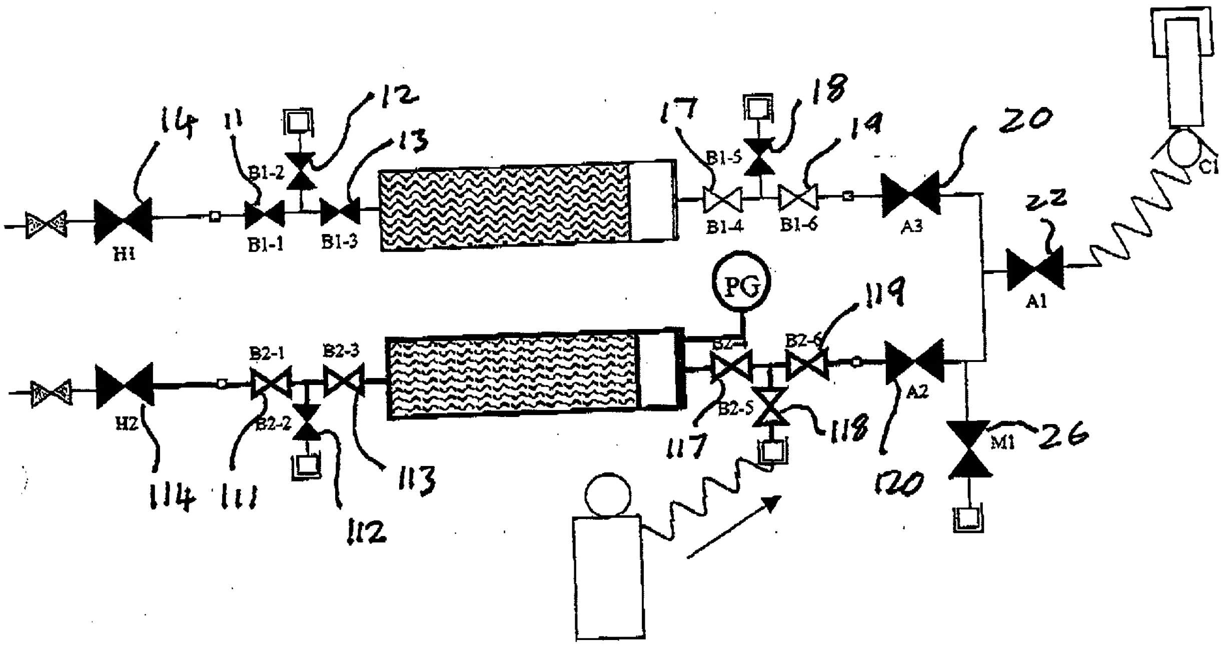

Fig. 17

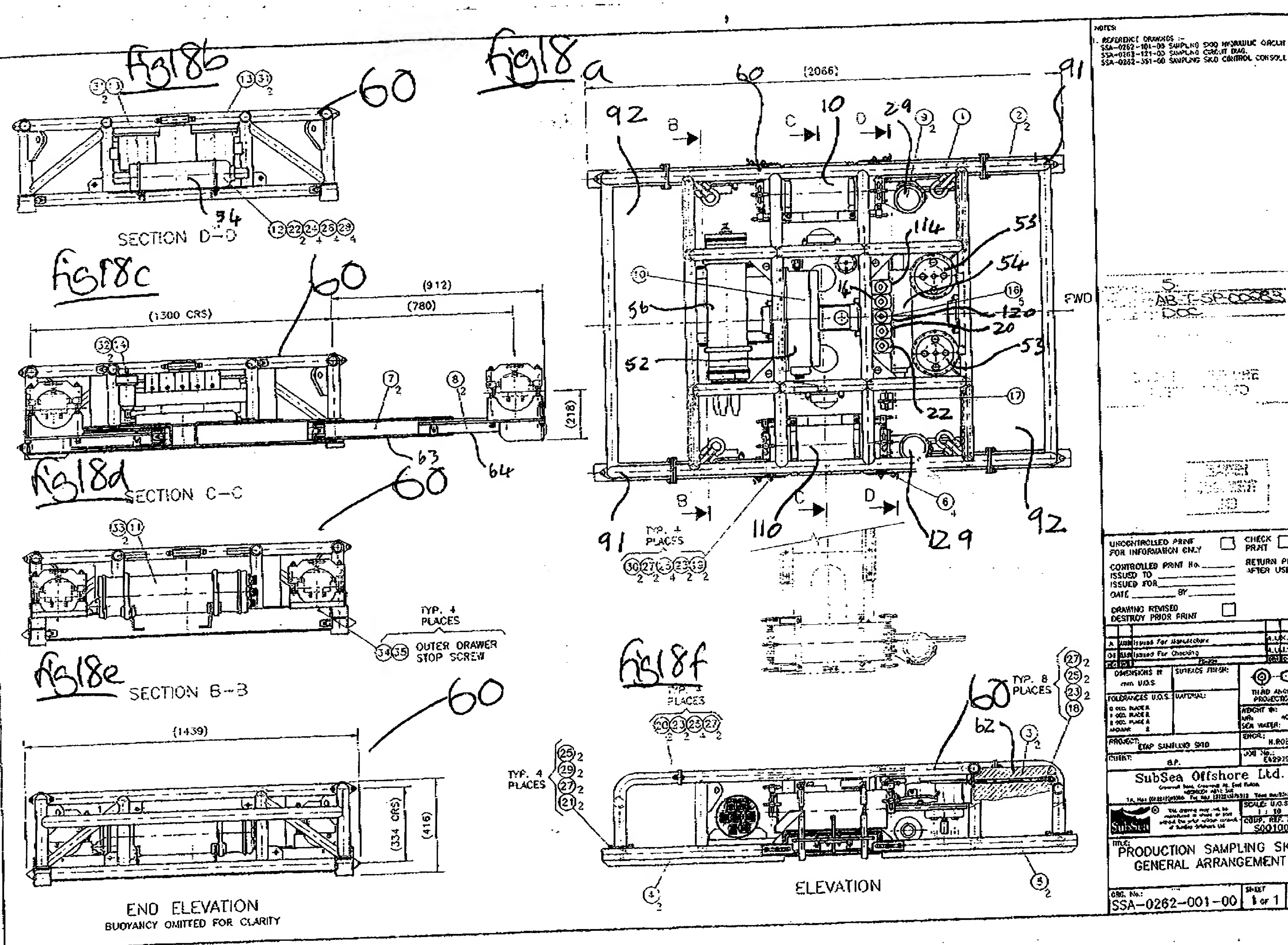
fig18a
fig18b
SECTION D-D
fig18c
SECTION C-C
fig18d
SECTION B-B
fig18e
END ELEVATION
BUOYANCY OMITTED FOR CLARITY
fig18f
ELEVATION
(2066)
(1300 CRS)
(912)
(780)
(218)
(1439)
(334 CRS)
(416)
TYP. 4 PLACES
OUTER DRAWER STOP SCREW
TYP. 8 PLACES
FWD
NOTES:
1. REFERENCE DRAWINGS :-
SSA-0262-101-00 SAMPLING SKID HYDRAULIC CIRCUIT
SSA-0262-121-00 SAMPLING CIRCUIT DIAG.
SSA-0262-351-00 SAMPLING SKID CONTROL CONSOLE
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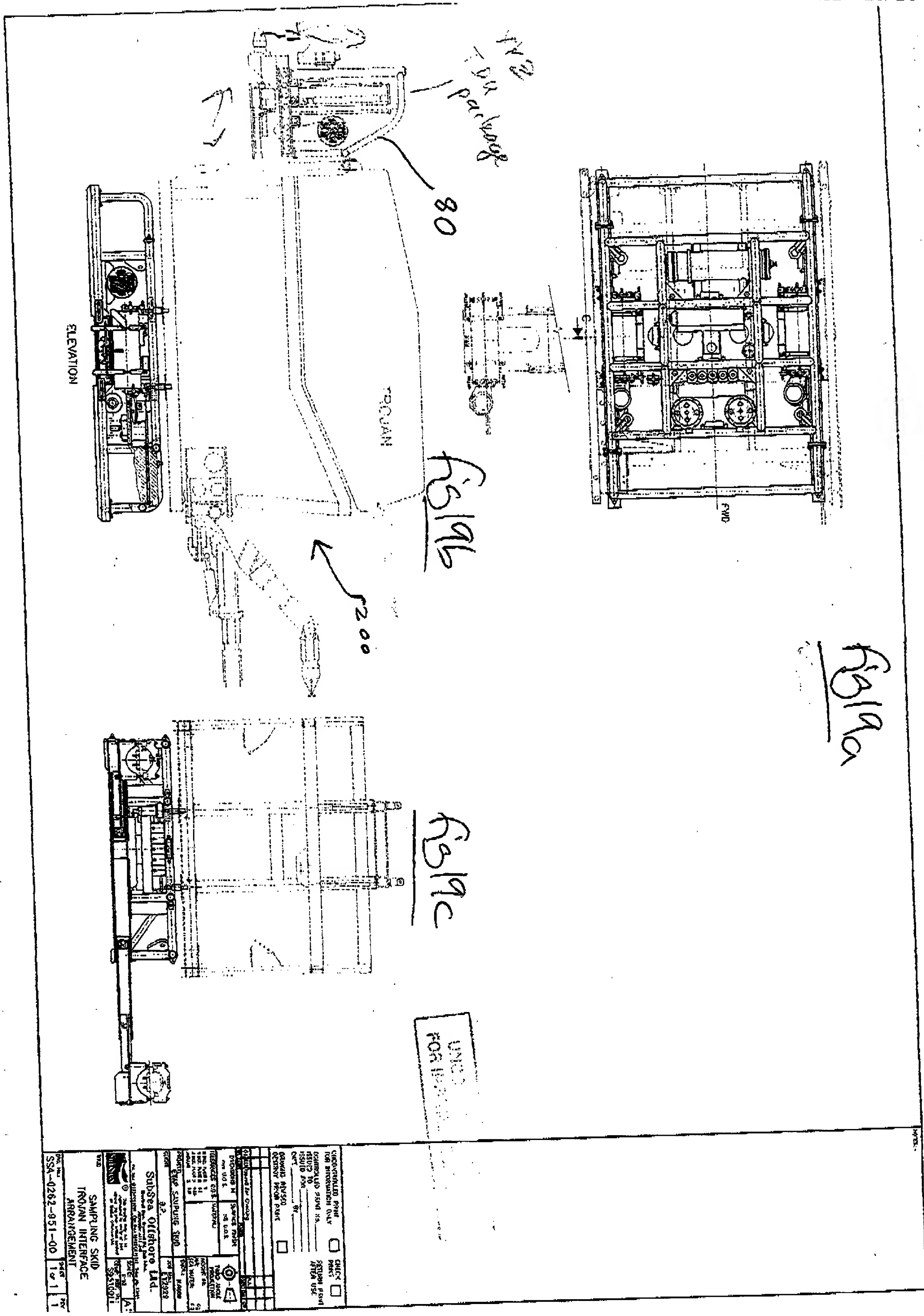
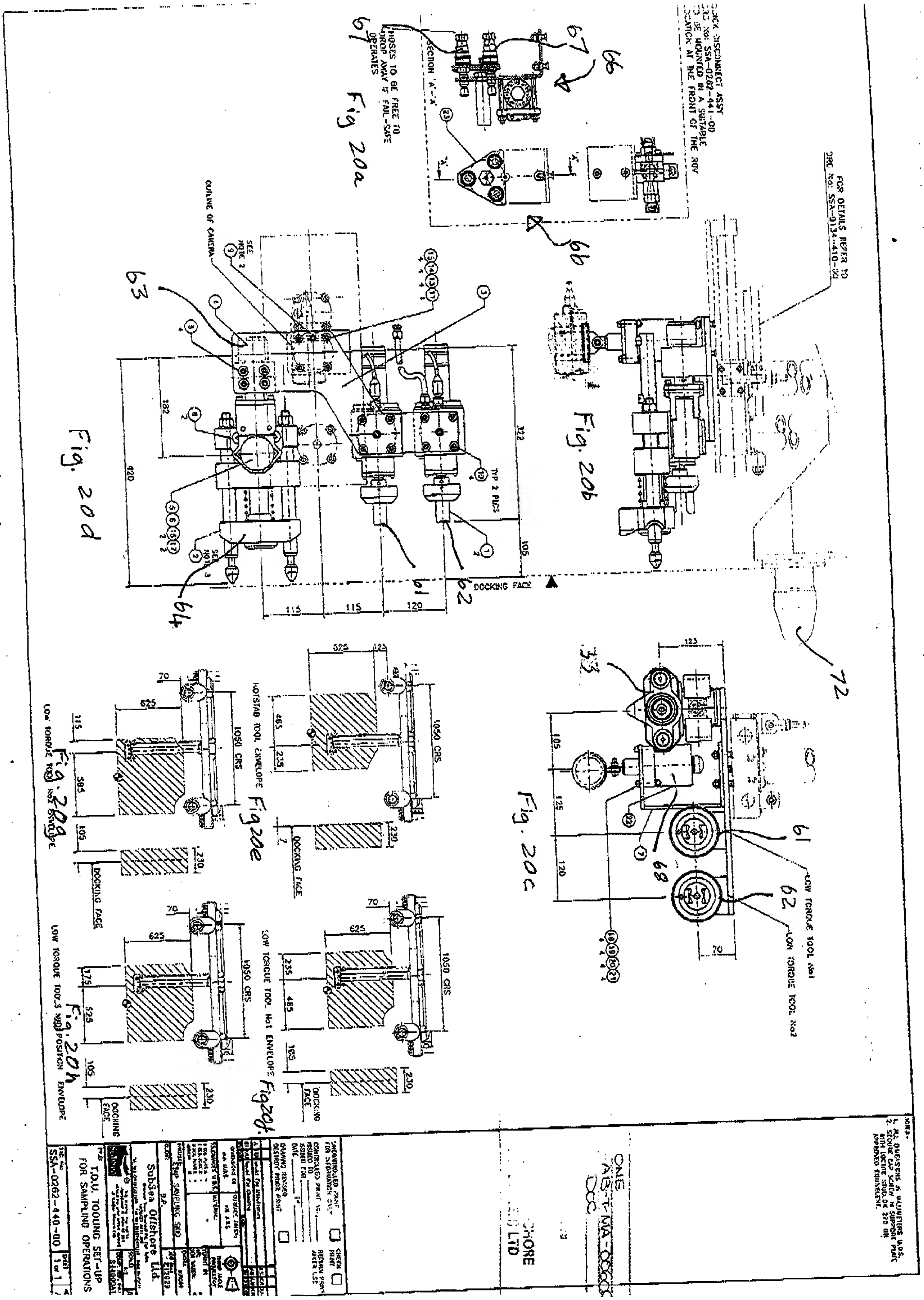
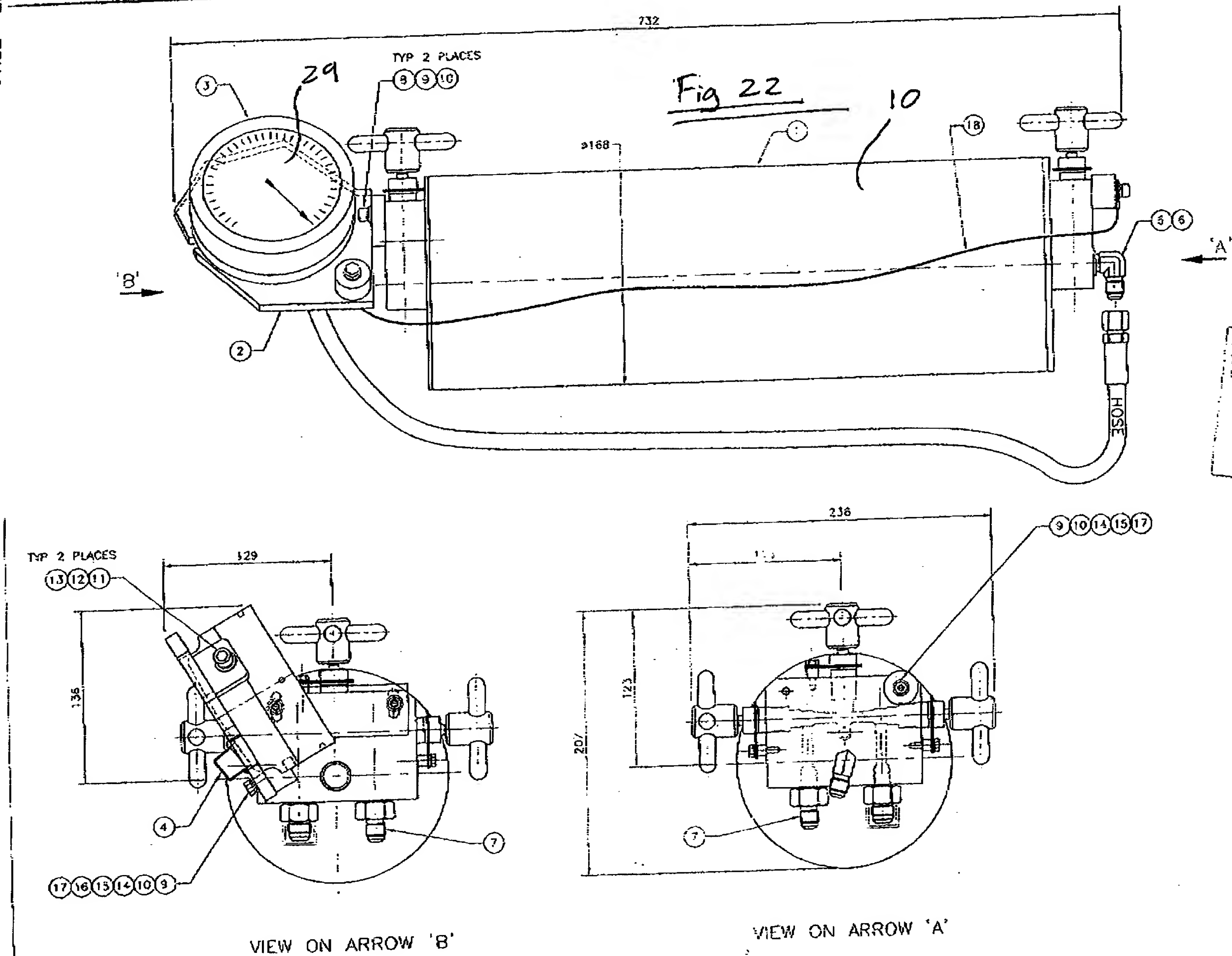
DIMENSIONS IN mm U.O.S.
SURFACE FINISH:
TOLERANCES U.O.S.
MATERIAL:
THIRD ANGLE PROJECTION
PROJECT: ETAP SAMPLING SKID
CLIENT: B.P.
SubSea Offshore Ltd.
SCALE: U.O.S. 1 : 10
TITLE: PRODUCTION SAMPLING SKID GENERAL ARRANGEMENT
DWG. No.: SSA-0262-001-00
SHEET 1 OF 1



09546256.041000



09546256 .041000



NOTES:
1. WORKING PRESSURE 230 BAR (335 P.S.I.)
2. TEST PRESSURE 345 BAR (5002 P.S.I.)
3. TEMPERATURE RANGE -30° TO 130°C
4. CAPACITY 3 LITRE
5. APPLICABLE CODES BS 5500 NACE MR 01-75

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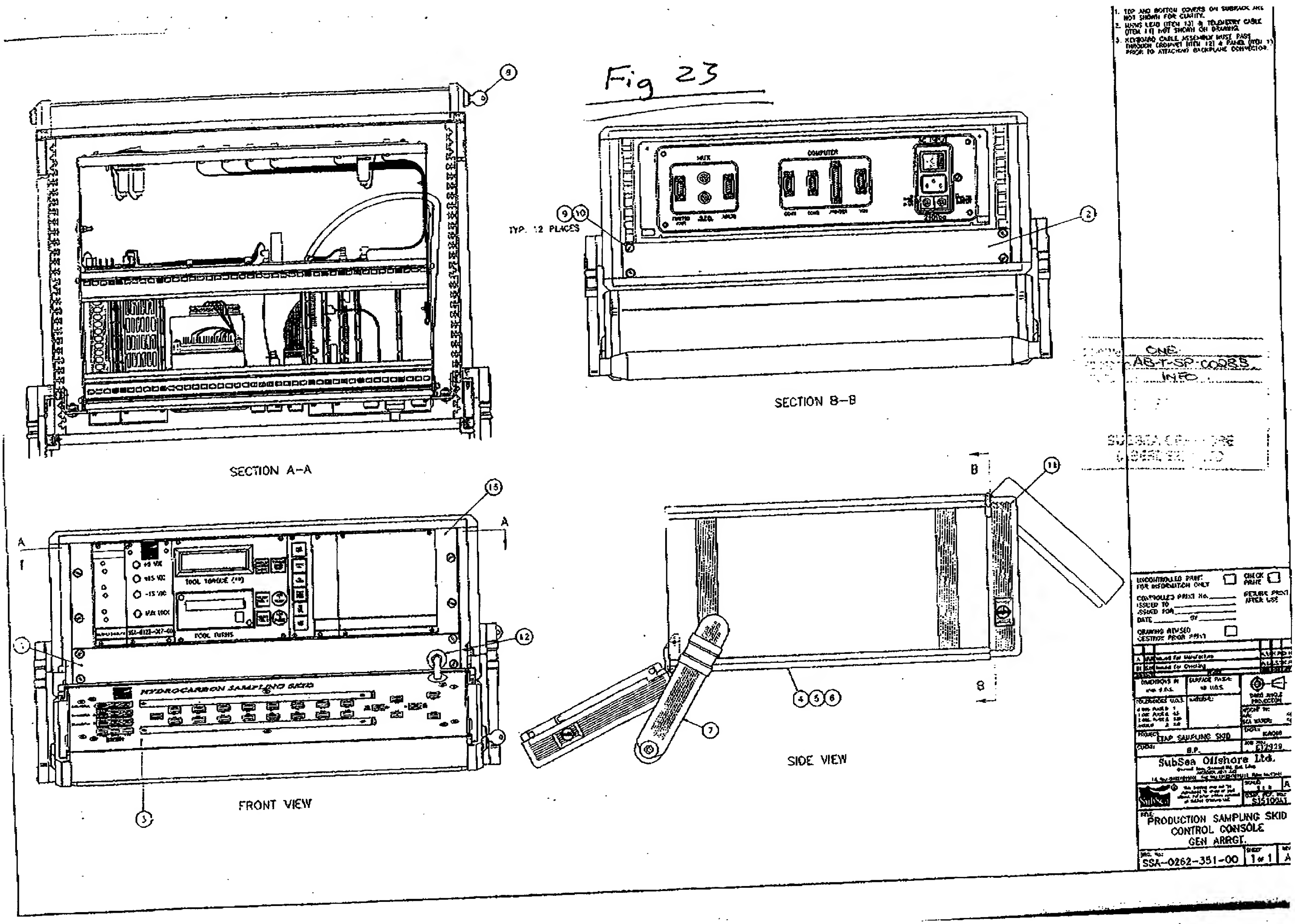
SubSea Offshore Ltd.

TITLE: PRODUCTION SAMPLING SKID SAMPLE BOTTLE PRESSURE GAUG G.A.

DRG. No.: SSA-0262-030-00 SHEET 1 of 1

09546256.041000



0954G256.041000

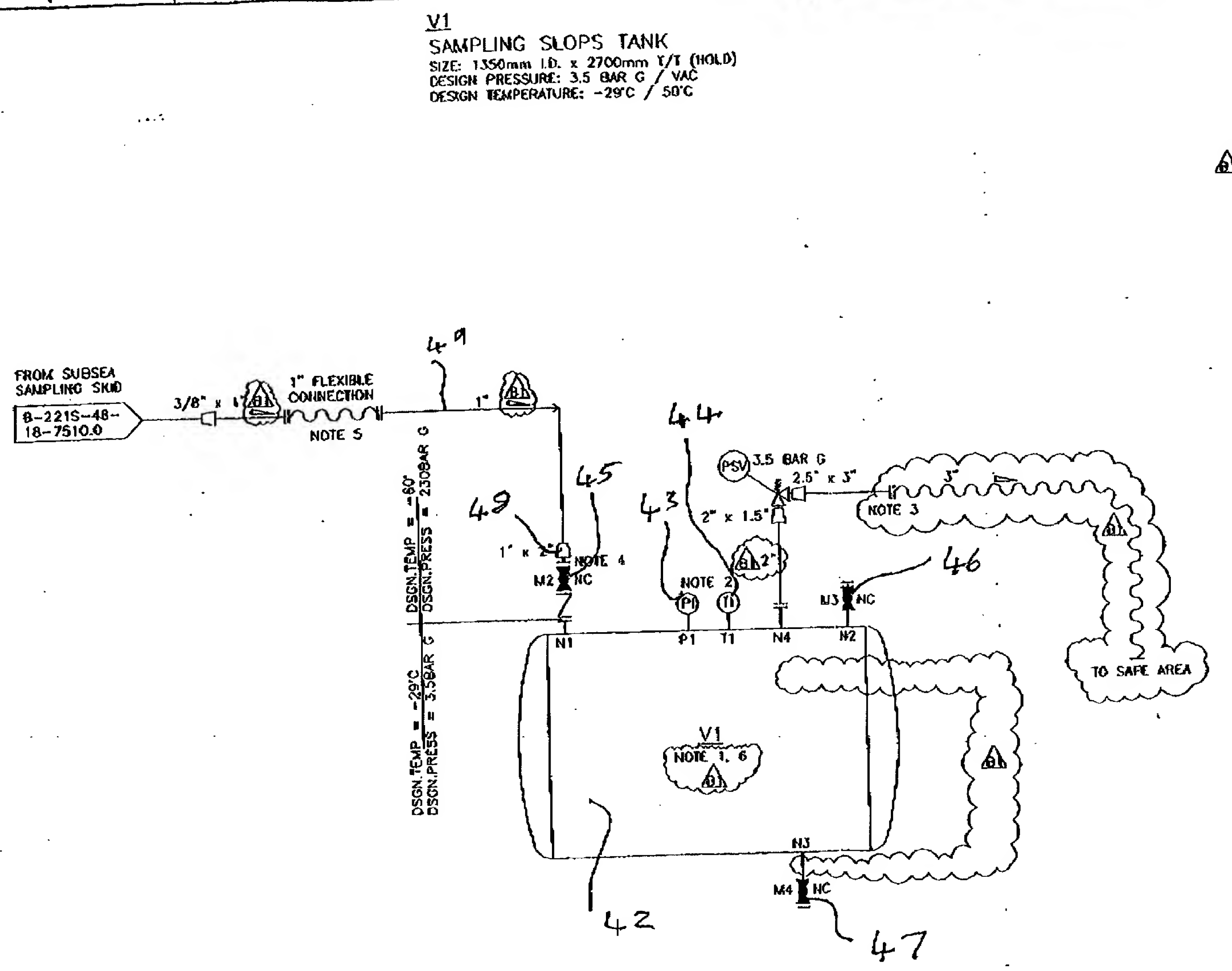


Fig 21

DO NOT SCALE | IF IN DOUBT ASK

NOTES:

1. SLOPS TANK NOT IN CONTINUOUS USE, TO BE DISCONNECTED & TAKEN TO SHORE FOR DISCHARGE OPERATION
2. PRESSURE & TEMPERATURE GAUGES TO BE VISIBLE FROM MANUAL CONTROL VALVE M1 SHOWN ON P & I.D. B-221S-48-18-7510.0
3. PSV DISCHARGE FLEXIBLE TO BE DISMANTABLE
4. BLIND FLANGE TO BE PROVIDED FOR POSITIVE ISOLATION AFTER THE INLET PIPING HAS BEEN DISCONNECTED
5. FLEXIBLE HOSE CONNECTION TO WITHSTAND MINIMUM FLUID TEMPERATURE
6. LEVEL TO BE MEASURED USING A PORTABLE NON INTRUSIVE LEVEL GAUGE B1

HOLDS:

1. LINE NUMBERS
2. TAG No's
3. PIPING SPECIFICATION & PIPING DESIGN DETAILS

REFERENCE DRAWINGS:

1. P & I.D. SUBSEA SAMPLING SKID B-221S-48-18-7510.0

Rev	Date	Revision	By	Chk'd Eng.	App Project
B1	02.11.98	APPROVED FOR ENQUIRY	AP	[illegible]	[illegible]
A2	12.10.98	ISSUED FOR HAZOP	AP	VB	JC
A1	21.09.98	ISSUED FOR CLIENT REVIEW	AP		

Client: BP ETAP

Rockwater

Draughtsman	Checker	Eng. Engineer	Lead Engineer	Project Manager	Approved
A.PROCTOR	R.ALOCKHART	C.COLLINGWOOD	V.BERNARDIN		
Date 17.09.98	Date 21.09.98	Date 21.09.98	Date 21.09.98	Date	Date

Sheet Size: A2 | Drawing & Plotting Scale: NTS | CAD File No. DE321002

Project: BP ETAP

Title: P & I.D. SLOPS TANK FOR SUBSEA SAMPLING SYSTEM

Dwg No. B-221S-48-18-7511.0 | Rev. B1

AutoCAD Produced Drawing - Do Not Change Manually

United States Patent Application

COMBINED DECLARATION AND POWER OF ATTORNEY

Attorney's Docket Number MUR-85094US

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled:

Method and Apparatus for Sampling Fluids from a Wellbore

the specification of which is attached hereto.

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, Code of Federal Regulations, Section 1.56(a).

POWER OF ATTORNEY: As a named inventor, I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and transact all business in the patent and Trademark Office connected therewith:

Paul F Prestia	Reg No 23,031	Christopher R Lewis	Reg No 36,201
Allan Ratner	Reg No 19,717	Louis W Beardell Jr	Reg No 40,506
Andrew L Ney	Reg No 20,300	Rocco L Adornato	Reg No 40,480
Kenneth N Nigon	Reg No 31,549	Jacques L Etkowicz	Reg No 41,738
Kevin R Casey	Reg No 32,117	Eric A Dichter	Reg No 41,708
Benjamin E Leace	Reg No 33,412	Mark F Marcelli	Reg No 38,593
James C Simmons	Reg No 24,842	Joshua L Cohen	Reg No 38,040
Lawrence E Ashery	Reg No 34,515	Christopher J Dervishian	Reg No 42,480
Robert L Anderson	Reg No 25,771	Jack J Jankovitz	Reg No 42,690

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Post office address: AB39 3TW.

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that wilful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code, and that such wilful false statements may jeopardize the validity of the application or any patent issuing thereon.

Signature of First Inventor ____________ Date 06/04/00

Signature of Second Inventor Kevin Robb Date 06/04/00